

dolfiny: Convenience wrappers for DOLFINx

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Motivation | why `dolfiny`?

DOLFINx advantages

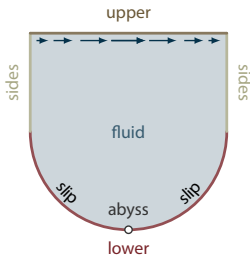
- ▶ access to low level interfaces, light core
- ▶ more flexible, more explicit
- ▶ demands bottleneck-awareness

DOLFINx shortcomings (today)

- ▶ user code often quite verbose
- ▶ increased complexity to end-user
- ▶ consistent approach to extensions?

`dolfiny`: Python, collection of wrappers, extensions + new functionality

Mesh and MeshTags | challenge: problem setup



- ▶ Gmsh to DOLFINx
- ▶ merge named non-overlapping MeshTags
- ▶ sub-classed XDMFFile

```
import mesh_cavity_gmshapi as mg
```

```
# Create the geometry/mesh of the cavity using Gmsh Python API  
gmsht, tdim = mg.mesh_cavity_gmshapi() # see demos in dolfinx repo
```

```
import dolfinx.mesh
```

```
# Get mesh and meshtags  
mesh, mts = dolfinx.mesh.gmsh_to_dolfin(gmsht, tdim, prune_z=True)
```

```
# Get merged MeshTags for each codimension  
subdomains, subdomains_keys = dolfinx.mesh.merge_meshtags(mts, tdim - 0)  
interfaces, interfaces_keys = dolfinx.mesh.merge_meshtags(mts, tdim - 1)  
markpoints, markpoints_keys = dolfinx.mesh.merge_meshtags(mts, tdim - 2)
```

```
# Define shorthands for labelled tags
```

```
fluid = subdomains_keys["fluid"]  
upper = interfaces_keys["upper"]  
lower = interfaces_keys["lower"]  
sides = interfaces_keys["sides"]  
abyss = markpoints_keys["abyss"]
```

```
import dolfinx.io
```

```
# Create output XDMF file  
ofile = dolfinx.io.XDMFFile(comm, f"{name}.xdmf", "w")
```

```
# Write mesh, meshtags  
ofile.write_mesh_meshtags(mesh, mts)
```

Restriction | challenge: weak interface constraints

```
import dolfinx, ufl

# Function spaces, functions and test functions
V, P, L = # ... e.g. dolfinx.VectorFunctionSpace(mesh, ("CG", 2))
v, p, lambda = # ... e.g. dolfinx.Function(V, name="v")
delta_v, delta_p, delta_lambda = # ... e.g. ufl.TestFunction(V)

# Integration measures
dx = ufl.Measure("dx", domain=mesh, subdomain_data=subdomains)
ds = ufl.Measure("ds", domain=mesh, subdomain_data=interfaces)

# Non-Newtonian fluid, with mu = mu(D)
D = ufl.sym(ufl.grad(v))
T = 2 * mu(D) * D - p * ufl.Identity(2)

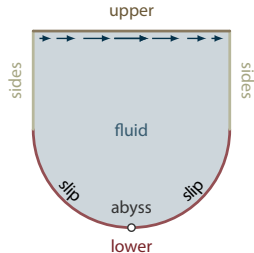
# Weak form (as one-form), with n = ufl.FacetNormal(mesh)
f = ufl.inner(ufl.grad(delta_v), T) * dx + delta_p * ufl.div(v) * dx \
    + ufl.dot(delta_v, n) * lambda * ds(lower) + delta_lambda * ufl.dot(v, n) * ds(lower)
```

```
import dolfiny.function

# Locate dofs: restriction
rdofsV = dolfiny.mesh.locate_dofs_topological(V, subdomains, fluid)
rdofsV = dolfiny.function.unroll_dofs(rdofsV, V.dofmap.bs)
rdofsP = dolfiny.mesh.locate_dofs_topological(P, subdomains, fluid)
rdofsL = dolfiny.mesh.locate_dofs_topological(L, interfaces, lower)

import dolfiny.restriction

# Set up restriction
r_fspaces, r_dofs = [V, P, L], [rdofsV, rdofsP, rdofsL]
restriction = dolfiny.restriction.Restriction(r_fspaces, r_dofs)
```



- ▶ restrict full function space to subset of dofs
- ▶ discrete/algebraic approach

SNES interface | challenge: nonlinear (restricted) problem

- ▶ SNESBlockProblem interfaces to PETSc SNES
- ▶ custom block-wise convergence monitors
- ▶ allows MatNest and AIJ/BAIJ as matrix storage layout
- ▶ supports restrictions

```
# Define state as (ordered) list of functions
m,  $\delta m$  = [v, p,  $\lambda$ ], [ $\delta v$ ,  $\delta p$ ,  $\delta \lambda$ ]

# Overall form (as list of forms)
F = dolfiny.function.extract_blocks(f,  $\delta m$ )

import dolfiny.snesblockproblem

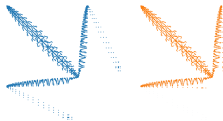
# Create nonlinear problem: SNES
problem = dolfiny.snesblockproblem.SNESBlockProblem(F, m, restriction)

# Set/update boundary conditions
problem.bcs = # ...

# Solve nonlinear problem
problem.solve()
```

```
### SNES iteration 4
# sub 0 |x|=1.652e+01 |dx|=2.515e-02 |r|=1.993e-03 (v)
# sub 1 |x|=1.359e+02 |dx|=7.764e-01 |r|=2.130e-17 (p)
# sub 2 |x|=4.723e+02 |dx|=2.218e+00 |r|=2.895e-18 ( $\lambda$ )
# o1l |x|=4.913e+02 |dx|=2.342e+00 |r|=1.993e-03

### SNES iteration 5
# sub 0 |x|=1.851e+01 |dx|=9.619e-04 |r|=3.658e-06 (v)
# sub 1 |x|=1.359e+02 |dx|=1.336e-02 |r|=1.890e-17 (p)
# sub 2 |x|=4.723e+02 |dx|=6.602e-03 |r|=1.713e-18 ( $\lambda$ )
# o1l |x|=4.913e+02 |dx|=1.497e-02 |r|=3.658e-06
...
```



- ▶ Restriction uses PETSc.Mat.createSubMatrix()

Interpolation | challenge: expression evaluation

- ▶ interpolate UFL expressions into functions
- ▶ supports arbitrary cell-wise UFL expressions: into CG/DG (FFCx/numba)
- ▶ supports linear combination of functions for arbitrary function spaces

Cell-wise

```
import dolfiny.interpolation

# Function space for interpolated stress tensor
S = dolfinx.TensorFunctionSpace(mesh, ("DG", 1), \
                                   symmetry=True)

# Function
s = dolfinx.Function(S)

# Interpolate UFL expression T
dolfiny.interpolation.interpolate(T, s)
```

Facet-wise (soon)

```
import dolfiny.interpolation

# Function space for interpolated stress vector
S = dolfinx.VectorFunctionSpace(mesh, ("DG", 1))

# Function
s = dolfinx.Function(S)

# Interpolate UFL expression T * n
dolfiny.interpolation.interpolate(T * n, s)
```

Time-dependent forms | challenge: ease-of-use

```
# Global time, Time step size
time, dt = dolfinx.Constant(mesh, 0.0), dolfinx.Constant(mesh, 0.1)

# Define functions representing 1st time derivative
vt, pt,  $\lambda$ t = # ... e.g. dolfinx.Function(V, name="vt"), ...

# Define state as (ordered) list of functions
m, mt,  $\delta$ m = [v, p,  $\lambda$ ], [vt, pt,  $\lambda$ t], [ $\delta$ v,  $\delta$ p,  $\delta$  $\lambda$ ]

import dolfiny.odeint

# Time integrator
odeint = dolfiny.odeint.ODEInt(t=time, dt=dt, x=m, xt=mt)

# Weak form (as one-form), with time-dependent terms
f = # ... \
    + ufl.inner( $\delta$ v, rho * vt + rho * ufl.grad(v) * v) * dx

# Overall form (as one-form)
F = odeint.discretise_in_time(f)

# Overall form (as list of forms)
F = dolfiny.function.extract_blocks(f,  $\delta$ m)

# Create nonlinear problem: SNES
problem = dolfiny.snesblockproblem.SNESBlockProblem(F, m, restriction)

# Time steps
for step in timesteps:
    odeint.stage()
    problem.solve()
    odeint.update()
```

- ▶ readability of forms
- ▶ single step methods
- ▶ stencil as expression
- ▶ expression-based state updates (interpolation)
- ▶ ODEInt, ODEInt2 for 1st/2nd order in time ODEs
- ▶ based on modified generalised- α method

Summary and outlook

<https://github.com/michalhabera/dolfiny>

Now

- ▶ transfer Gmsh/DOLFINx
- ▶ Restriction
- ▶ interpolation, projection
- ▶ SNESBlockProblem, SLEPcBlockProblem
- ▶ ODEInt, ODEInt2
- ▶ supports MPI parallelism
- ▶ various demos

Future

- ▶ interpolation on facets
- ▶ flexible API for static condensation
- ▶ ...