

# Working with Complex Meshes : The Mesh Processing Pipeline

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# Motivation

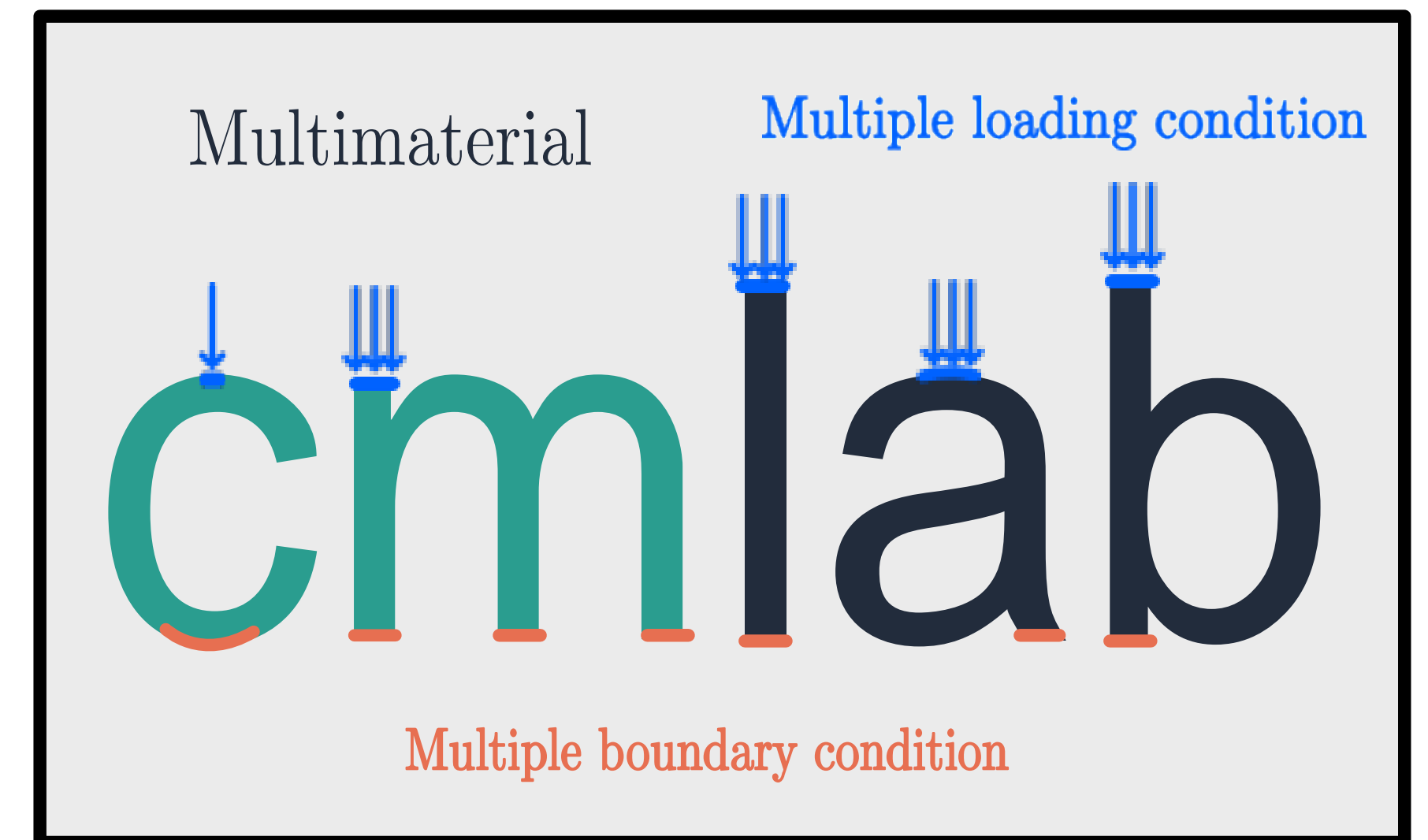
We wish to use FEniCS with complex geometries

In practice, a real world engineering structure could have :

1. Multiple loading areas
2. Multiple boundary conditions
3. Multiple materials

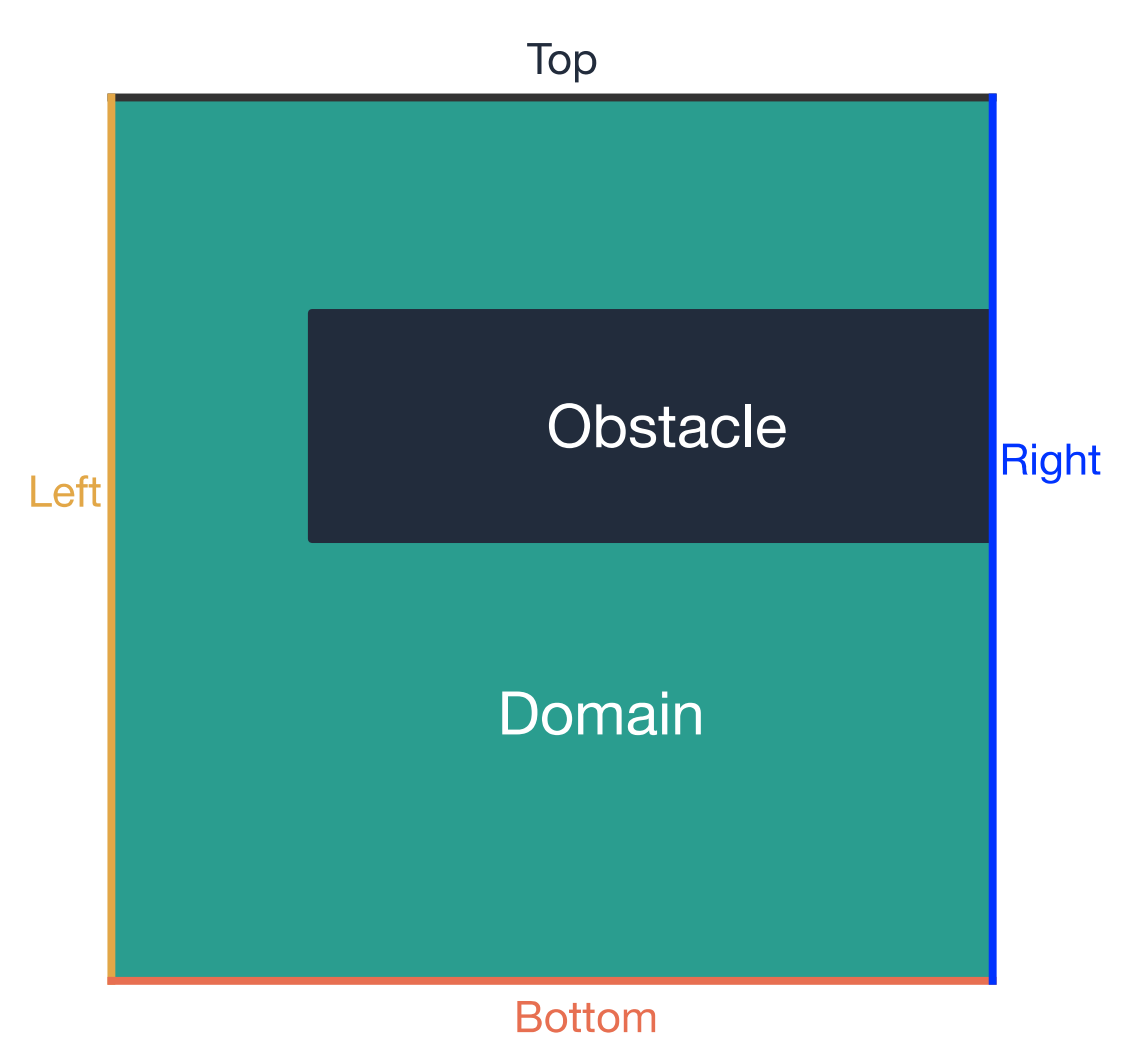
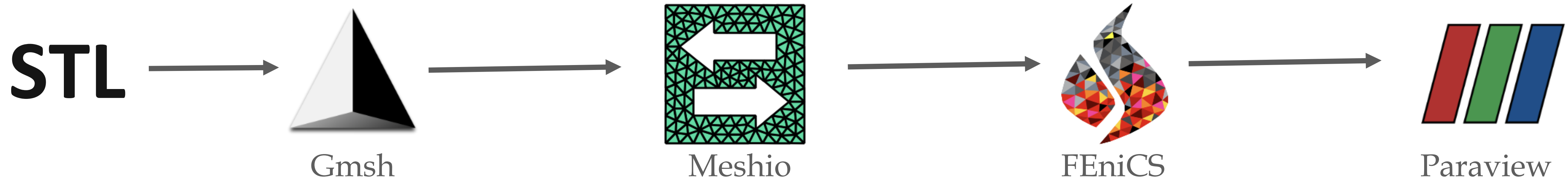
Thus can have 10 – 100's of marked regions in the mesh

**Problem:** This could result in human error in the process of modelling



“Output of a simulation is as good as the accuracy in the mathematical modelling”

# Preferred mesh processing pipeline



```

$PhysicalNames
6
1 3 "Top"
1 4 "Right"
1 5 "Left"
1 6 "Bottom"
2 1 "Domain"
2 2 "Obstacle"
$EndPhysicalNames
    
```

```

# Define Dirichlet boundary conditions at top and bottom boundaries
bcs = [DirichletBC(V, 5.0, boundaries, 2),
        DirichletBC(V, 0.0, boundaries, 4)]

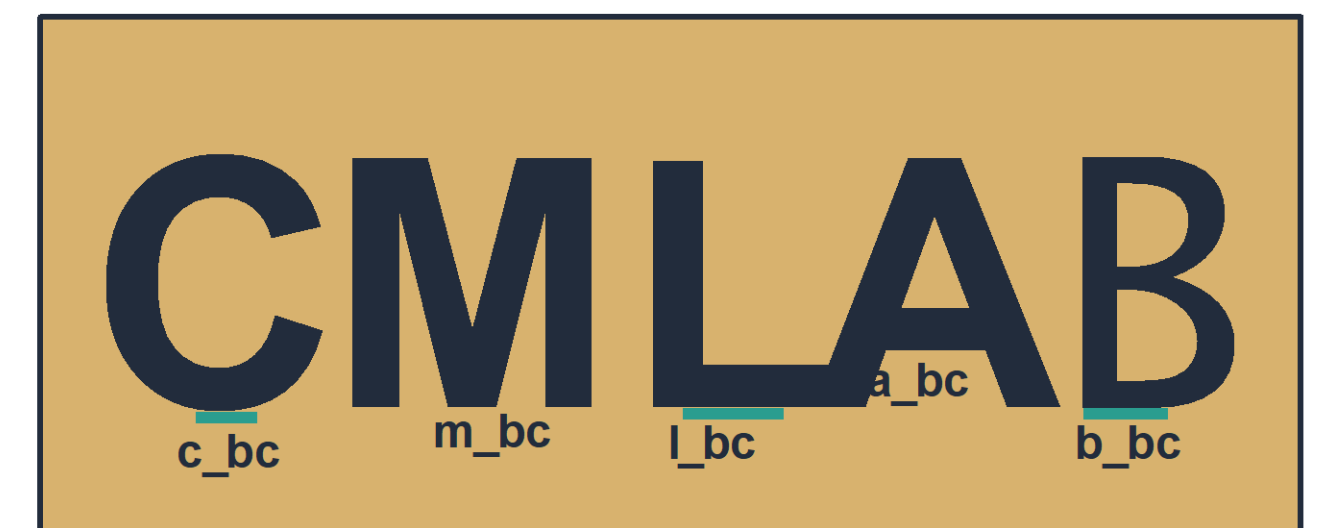
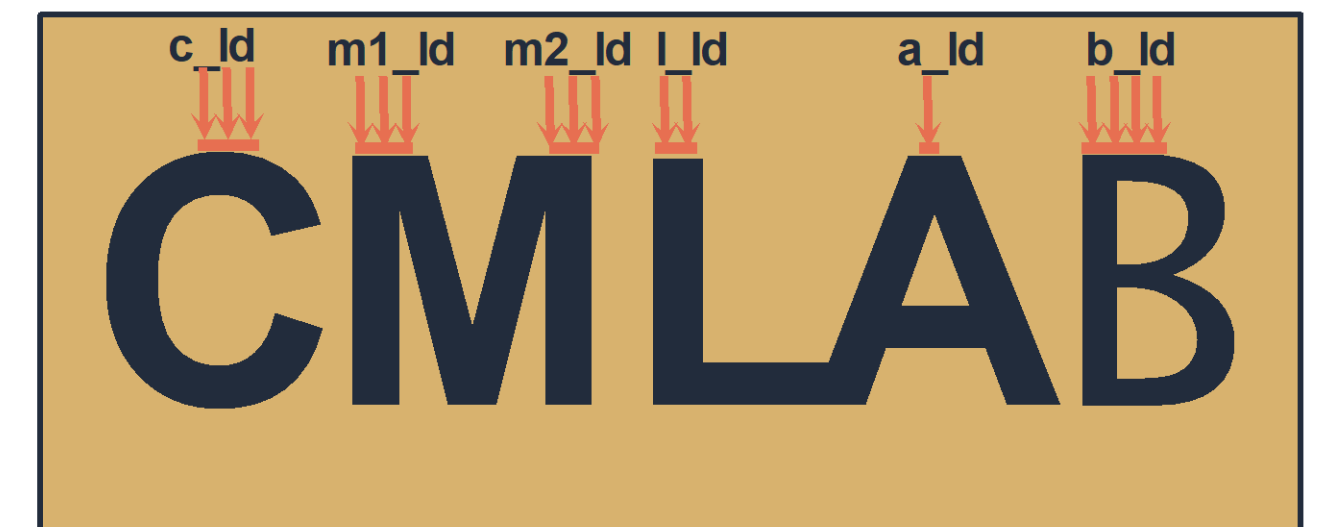
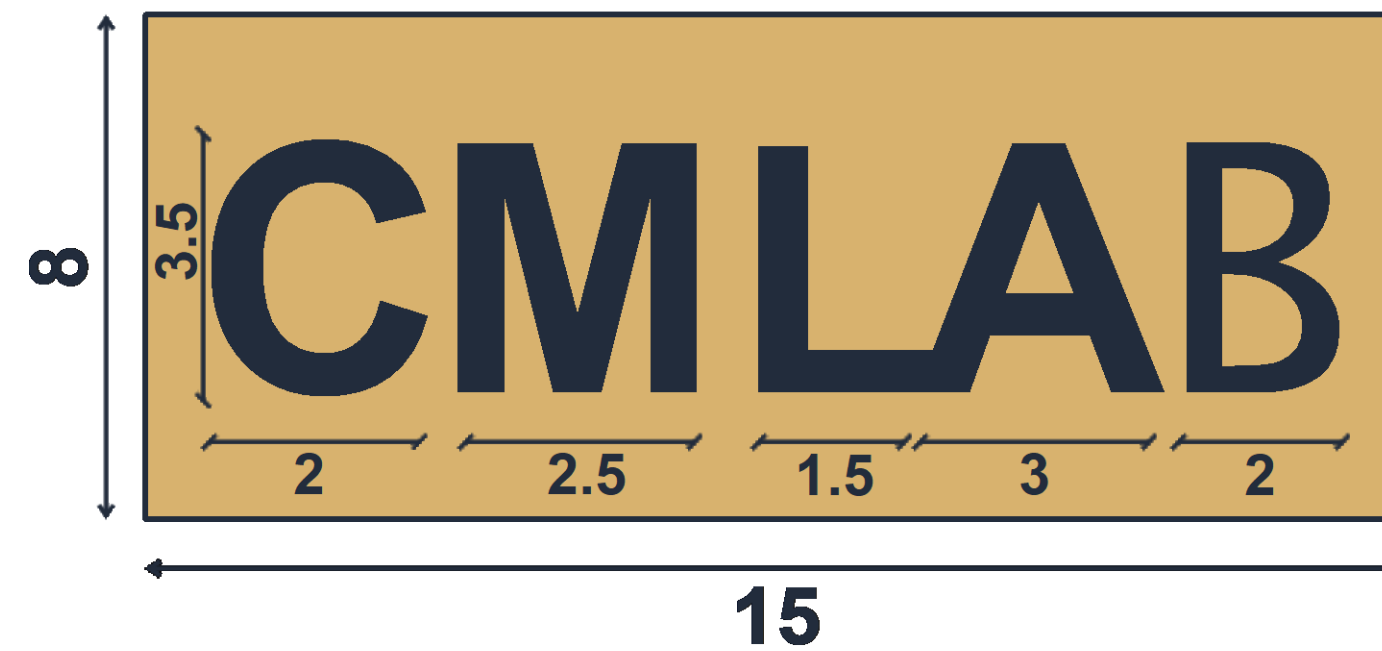
# Define new measures associated with the interior domains and
# exterior boundaries
dx = Measure("dx")[domains]
ds = Measure("ds")[boundaries]

# Define variational form
F = (inner(a0*grad(u), grad(v))*dx(0) + inner(a1*grad(u), grad(v))*dx(1)
      - g_L*v*ds(1) - g_R*v*ds(3)
      - f*v*dx(0) - f*v*dx(1))
    
```

# Basic design approach

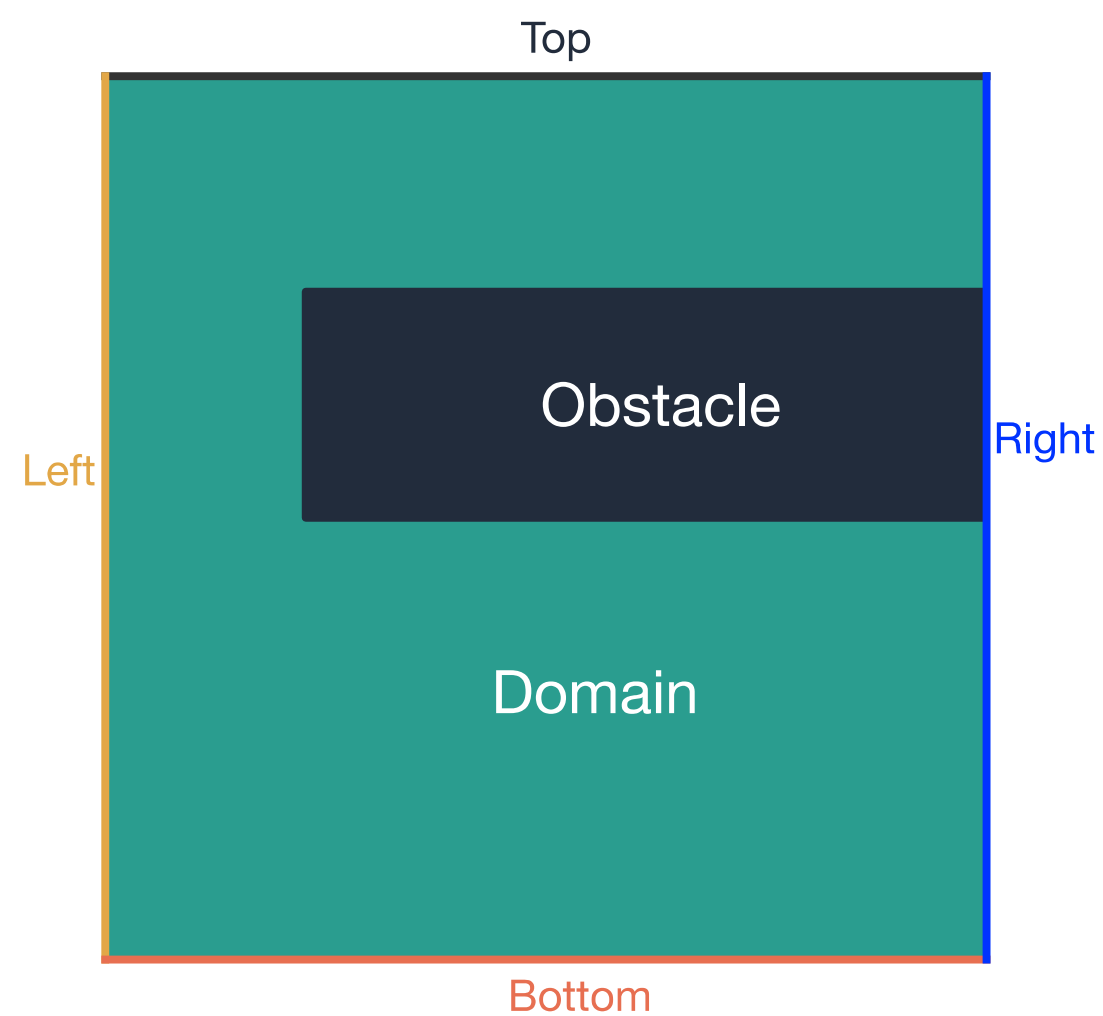
Engineering structures are accompanied with schematic drawings

1. Layout of the structure
2. Details of boundary conditions
3. Details of loading condition
4. Details about material properties



Aim : To use the same tag names which is in the schematic drawing in the FEniCS implementation

# Desired mesh processing pipeline



```

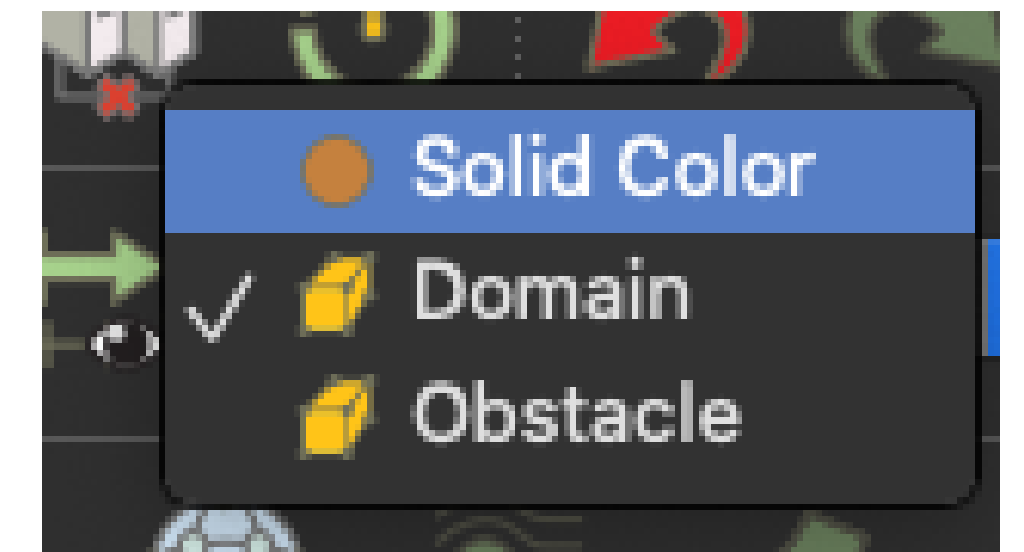
$PhysicalNames
6
1 3 "Top"
1 4 "Right"
1 5 "Left"
1 6 "Bottom"
2 1 "Domain"
2 2 "Obstacle"
$EndPhysicalNames
    
```

```

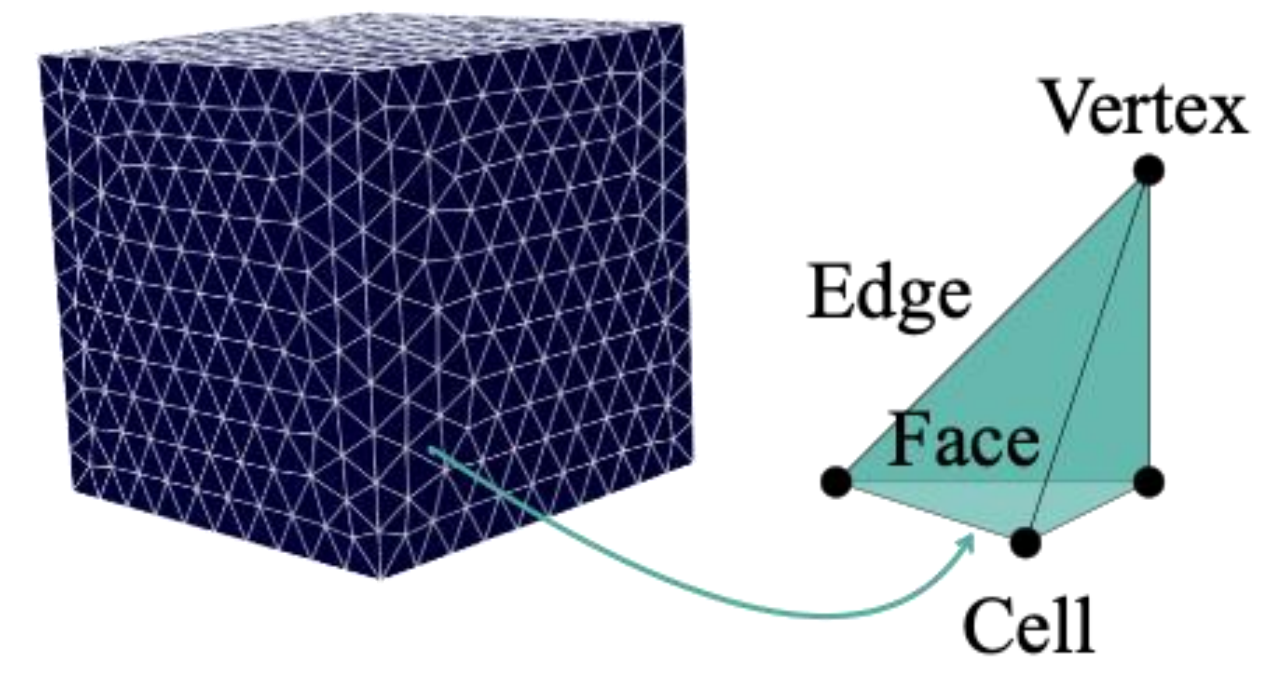
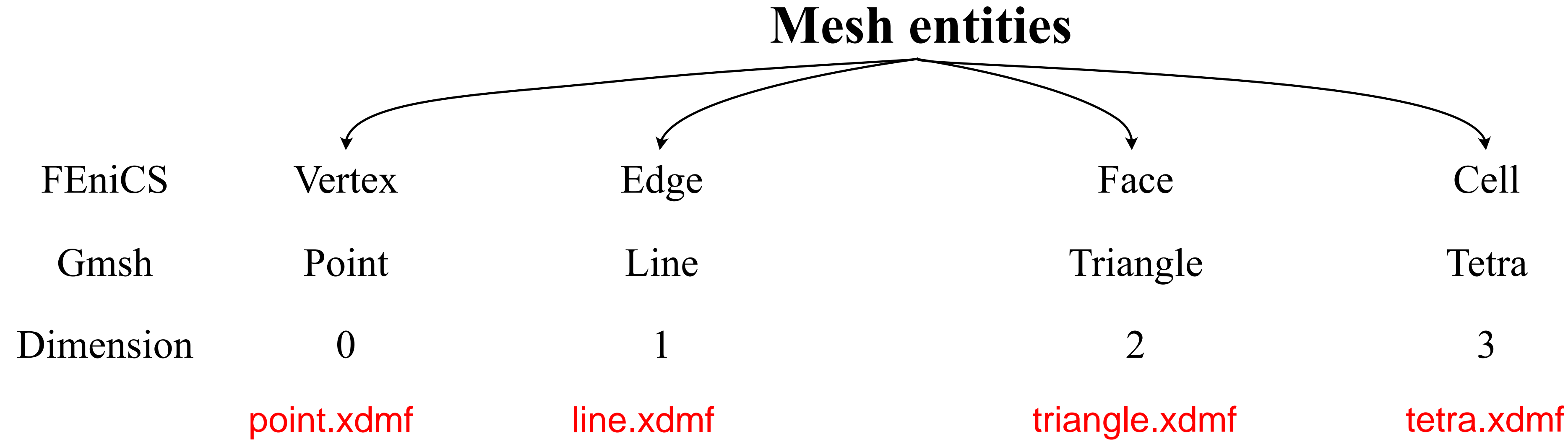
# Define Dirichlet boundary conditions at top and bottom boundaries
bcs = [DirichletBC(V, 5.0, boundaries, tags[ 'Top' ]),
       DirichletBC(V, 0.0, boundaries, tags[ 'Bottom' ])]

# Define new measures associated with the interior domains and
# exterior boundaries
dx = Measure("dx")[domains]
ds = Measure("ds")[boundaries]

# Define variational form
F = (inner(a0*grad(u), grad(v))*dx(tags[ 'Domain' ])
     + inner(a1*grad(u), grad(v))*dx(tags[ 'Obstacle' ])
     - g_L*v*ds(tags[ 'Left' ]) - g_R*v*ds(tags[ 'Right' ])
     - f*v*dx(tags[ 'Domain' ]) - f*v*dx(tags[ 'Obstacle' ]))
    
```



# Basis for Meshx



```
{
  "Top": 3,
  "Right": 4,
  "Left": 5,
  "Bottom": 6,
  "Domain": 1,
  "Obstacle": 2
}
```

**tags.json**

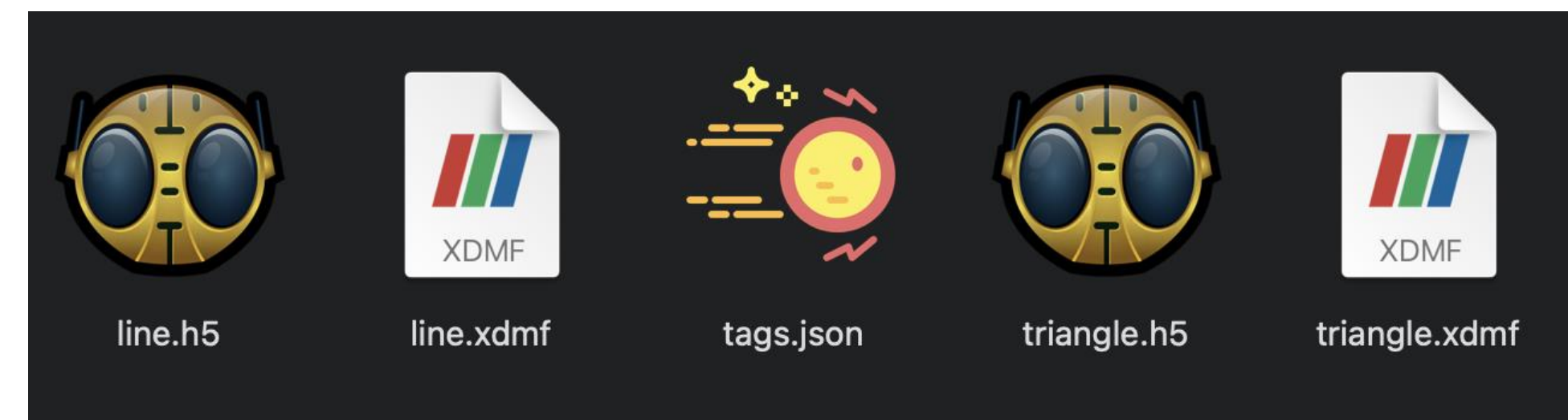
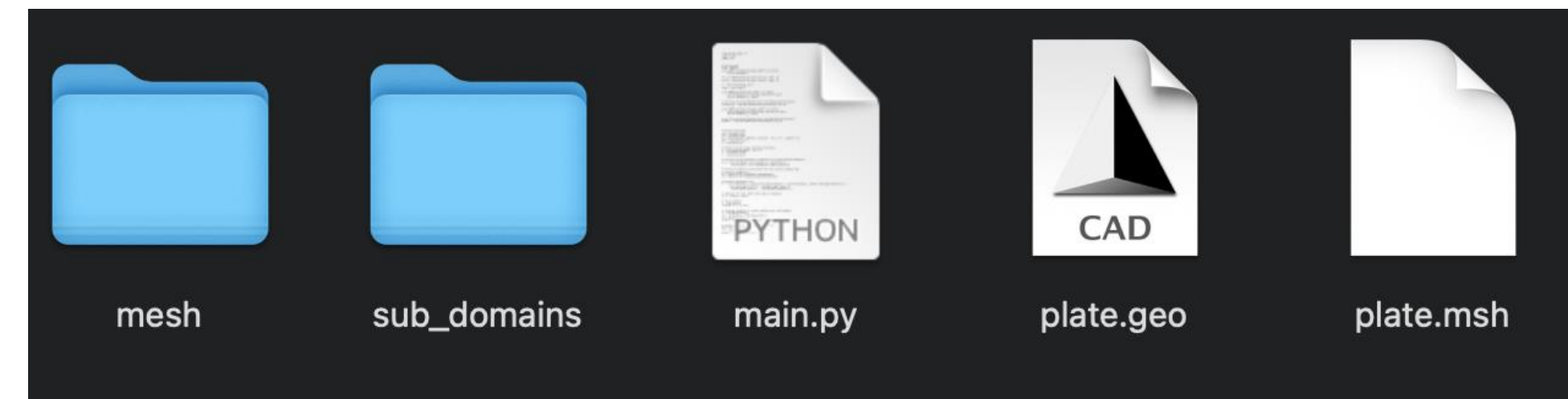
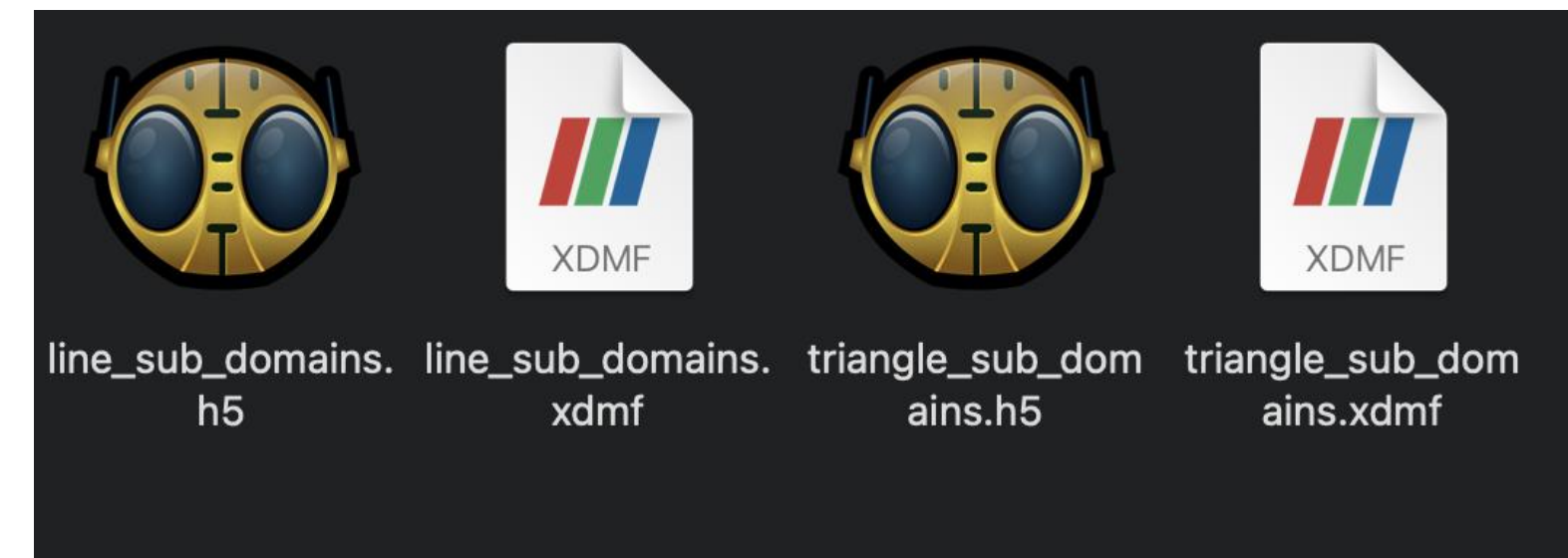
```
domain_mvc = MeshValueCollection("size_t", mesh, dim)
with XDMFFile("mesh/triangle.xdmf") as infile:
    infile.read(domain_mvc, "tag")
domain = cpp.mesh.MeshFunctionSizet(mesh, domain_mvc)

f = open('mesh/tags.json')
tags = json.load(f)
```

```
# Define variational form
F = (inner(a0*grad(u), grad(v))*dx(tags['Domain']))
      + inner(a1*grad(u), grad(v))*dx(tags['Obstacle'])
      - g_L*v*ds(tags['Left']) - g_R*v*ds(tags['Right'])
      - f*v*dx(tags['Domain']) - f*v*dx(tags['Obstacle']))
```

# Example:

```
→ root cd Codes/  
→ Codes cd poisson/  
→ poisson ls  
main.py plate.geo plate.msh  
→ poisson meshx plate.msh  
String tag      Num Tag      Dim  
-----  
Top             3           1  
Right          4           1  
Left           5           1  
Bottom         6           1  
Domain         1           2  
Obstacle       2           2  
Creating line mesh  
Creating triangle mesh  
XDMF created! 🎉🥳  
→ poisson ls  
main.py mesh plate.geo plate.msh sub_domains  
→ poisson python3 main.py
```



GitHub repository for meshx:

<https://github.com/iitrabhi/meshx>

You can use this Docker image:

<https://github.com/iitrabhi/fenics-docker>

# Thank You....

(computationalmechanics.in)