



UNIVERSITY OF
OXFORD

Mathematical
Institute

Piola-mapped finite elements for linear elasticity and Stokes flow

FRANCIS AZNARAN *, PATRICK FARRELL *, ROBERT KIRBY †

* *University of Oxford, UK*

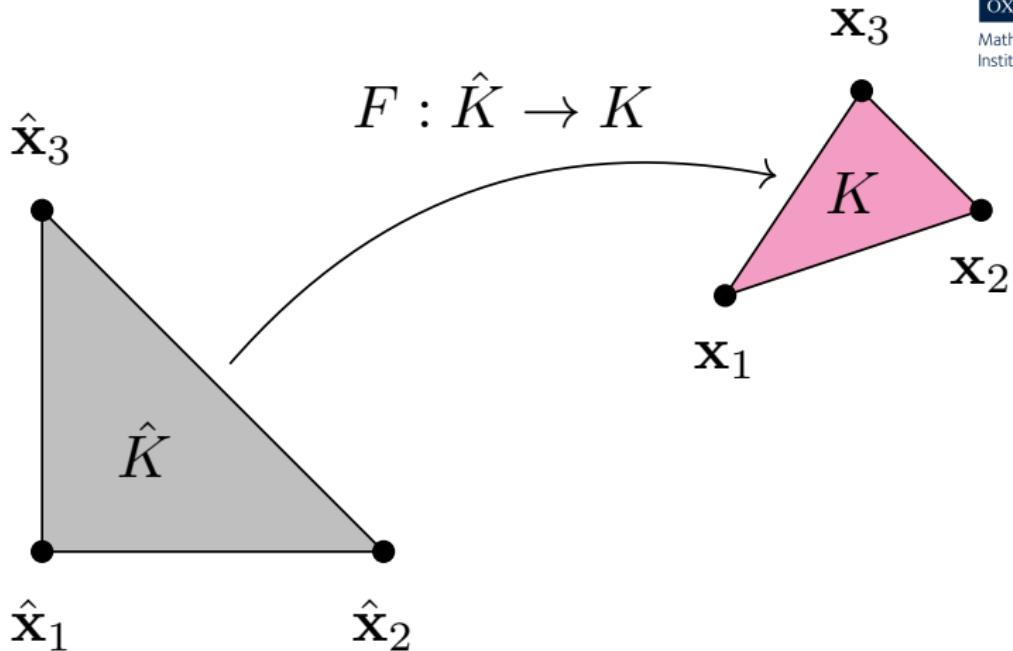
† *Baylor University, TX*

FEniCS 2021
23rd March 2021



Motivation

The reference element



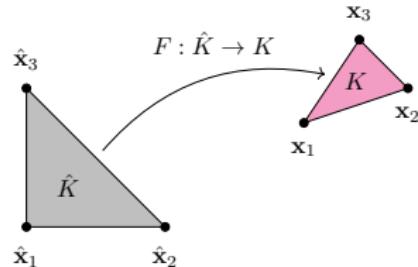
Motivation

The reference-to-physical map $F : K \rightarrow \hat{K}$ between cells

$$F(\hat{\mathbf{x}}) = J\hat{\mathbf{x}} + \mathbf{b}$$

induces a *pullback operator* on reference functions $\hat{\phi}$:

$$\left(\hat{\mathbf{x}} \mapsto \hat{\phi}(\hat{\mathbf{x}}) \right) \mapsto \left(\mathbf{x} \mapsto \phi(\mathbf{x}) := \hat{\phi}(F^{-1}(\mathbf{x})) \right).$$



Motivation

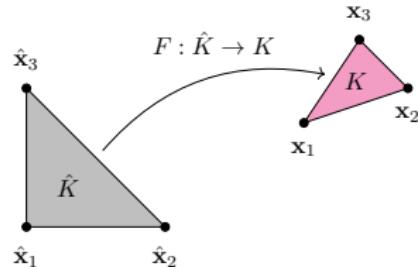
The reference-to-physical map $F : K \rightarrow \hat{K}$ between cells

$$F(\hat{\mathbf{x}}) = J\hat{\mathbf{x}} + \mathbf{b}$$

induces a *pullback operator* on reference functions $\hat{\phi}$:

$$\left(\hat{\mathbf{x}} \mapsto \hat{\phi}(\hat{\mathbf{x}}) \right) \mapsto \left(\mathbf{x} \mapsto \phi(\mathbf{x}) := \hat{\phi}(F^{-1}(\mathbf{x})) \right).$$

- Standard pullback preserves bases of **affine equivalent** elements:
Lagrange, Crouzeix–Raviart, ...



Motivation

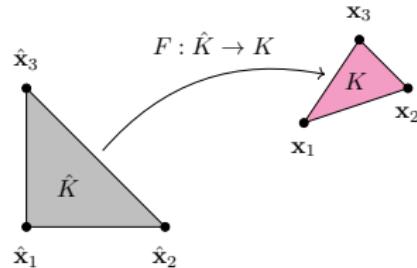
The reference-to-physical map $F : K \rightarrow \hat{K}$ between cells

$$F(\hat{\mathbf{x}}) = J\hat{\mathbf{x}} + \mathbf{b}$$

induces a *pullback operator* on reference functions $\hat{\phi}$:

$$\left(\hat{\mathbf{x}} \mapsto \hat{\phi}(\hat{\mathbf{x}}) \right) \mapsto \left(\mathbf{x} \mapsto \phi(\mathbf{x}) := \hat{\phi}(F^{-1}(\mathbf{x})) \right).$$

- Standard pullback preserves bases of **affine equivalent** elements: Lagrange, Crouzeix–Raviart, ...
- Many elements are **not preserved**: Hermite, Argyris, Morley, Bell, ...



Motivation

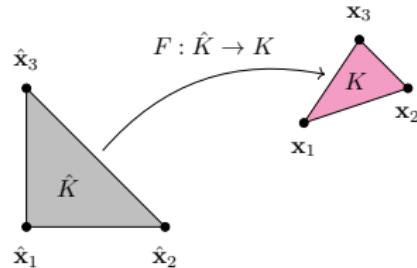
The reference-to-physical map $F : K \rightarrow \hat{K}$ between cells

$$F(\hat{\mathbf{x}}) = J\hat{\mathbf{x}} + \mathbf{b}$$

induces a *pullback operator* on reference functions $\hat{\phi}$:

$$\left(\hat{\mathbf{x}} \mapsto \hat{\phi}(\hat{\mathbf{x}}) \right) \mapsto \left(\mathbf{x} \mapsto \phi(\mathbf{x}) := \hat{\phi}(F^{-1}(\mathbf{x})) \right).$$

- Standard pullback preserves bases of **affine equivalent** elements: Lagrange, Crouzeix–Raviart, ...
- Many elements are **not preserved**: Hermite, Argyris, Morley, Bell, ...
- Transformation theory of [Kirby \[2018\]](#) showed how to obtain the correct bases on a generic physical cell.



Motivation

The reference-to-physical map $F : K \rightarrow \hat{K}$ between cells

$$F(\hat{\mathbf{x}}) = J\hat{\mathbf{x}} + \mathbf{b}$$

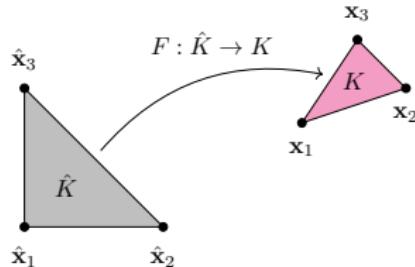
induces a *pullback operator* on reference functions $\hat{\phi}$:

$$\left(\hat{\mathbf{x}} \mapsto \hat{\phi}(\hat{\mathbf{x}}) \right) \mapsto \left(\mathbf{x} \mapsto \phi(\mathbf{x}) := \hat{\phi}(F^{-1}(\mathbf{x})) \right).$$

- Standard pullback preserves bases of **affine equivalent** elements: Lagrange, Crouzeix–Raviart, ...
- Many elements are **not preserved**: Hermite, Argyris, Morley, Bell, ...
- Transformation theory of [Kirby \[2018\]](#) showed how to obtain the correct bases on a generic physical cell.

Goal of this work:

Extend this theory to $H(\text{div})$ elements.



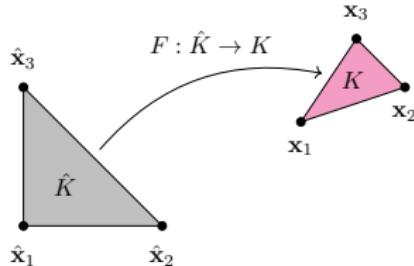
Motivation

The reference-to-physical map $F : K \rightarrow \hat{K}$ between cells

$$F(\hat{\mathbf{x}}) = J\hat{\mathbf{x}} + \mathbf{b}$$

induces a *pullback operator* on reference functions $\hat{\phi}$:

$$\left(\hat{\mathbf{x}} \mapsto \hat{\phi}(\hat{\mathbf{x}}) \right) \mapsto \left(\mathbf{x} \mapsto \phi(\mathbf{x}) := \hat{\phi}(F^{-1}(\mathbf{x})) \right).$$



- Standard pullback preserves bases of **affine equivalent** elements: Lagrange, Crouzeix–Raviart, ...
- Many elements are **not preserved**: Hermite, Argyris, Morley, Bell, ...
- Transformation theory of [Kirby \[2018\]](#) showed how to obtain the correct bases on a generic physical cell.

Goal of this work:

Extend this theory to $H(\text{div})$ elements.

Representative elements: $\begin{cases} H(\text{div}) : \text{Mardal–Tai–Winther } [2002]. \\ H(\text{div}; \mathbb{S}) : \text{Arnold–Winther } [2002, 2003]. \end{cases}$

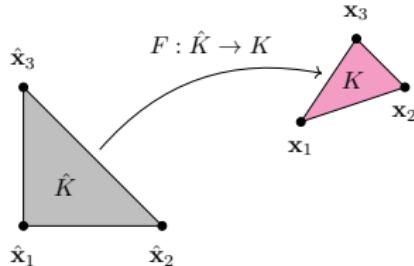
Motivation

The reference-to-physical map $F : K \rightarrow \hat{K}$ between cells

$$F(\hat{\mathbf{x}}) = J\hat{\mathbf{x}} + \mathbf{b}$$

induces a *pullback operator* on reference functions $\hat{\phi}$:

$$\left(\hat{\mathbf{x}} \mapsto \hat{\phi}(\hat{\mathbf{x}}) \right) \mapsto \left(\mathbf{x} \mapsto \phi(\mathbf{x}) := \hat{\phi}(F^{-1}(\mathbf{x})) \right).$$



- Standard pullback preserves bases of **affine equivalent** elements: Lagrange, Crouzeix–Raviart, ...
- Many elements are **not preserved**: Hermite, Argyris, Morley, Bell, ...
- Transformation theory of [Kirby \[2018\]](#) showed how to obtain the correct bases on a generic physical cell.

Goal of this work:

Extend this theory to $H(\text{div})$ elements.

Representative elements: $\begin{cases} H(\text{div}) : \text{Mardal–Tai–Winther } [2002]. \\ H(\text{div}; \mathbb{S}) : \text{Arnold–Winther } [2002, 2003]. \end{cases}$

Definition

Let $F : \hat{K} \rightarrow K$, $J(\hat{\mathbf{x}}) = \hat{\nabla}F(\hat{\mathbf{x}})$ its Jacobian. The *contravariant Piola transform* takes

$$\begin{aligned} \left(\hat{\Phi} : \hat{K} \rightarrow \mathbb{R}^d \right) &\mapsto \left(\mathcal{F}^{\text{div}}(\hat{\Phi}) = \Phi : K \rightarrow \mathbb{R}^d \right), \\ \mathcal{F}^{\text{div}}(\hat{\Phi}) &:= \frac{1}{\det J} J \hat{\Phi} \circ F^{-1}. \end{aligned}$$

Definition

Let $F : \hat{K} \rightarrow K$, $J(\hat{\mathbf{x}}) = \hat{\nabla}F(\hat{\mathbf{x}})$ its Jacobian. The *contravariant Piola transform* takes

$$\begin{aligned} \left(\hat{\Phi} : \hat{K} \rightarrow \mathbb{R}^d \right) &\mapsto \left(\mathcal{F}^{\text{div}}(\hat{\Phi}) = \Phi : K \rightarrow \mathbb{R}^d \right), \\ \mathcal{F}^{\text{div}}(\hat{\Phi}) &:= \frac{1}{\det J} J \hat{\Phi} \circ F^{-1}. \end{aligned}$$

The *double contravariant Piola transform* is

$$\begin{aligned} \left(\hat{\tau} : \hat{K} \rightarrow \mathbb{S} \right) &\mapsto \left(\mathcal{F}^{\text{div},\text{div}}(\hat{\tau}) = \tau : K \rightarrow \mathbb{S} \right), \\ \mathcal{F}^{\text{div},\text{div}}(\hat{\tau}) &:= \frac{1}{(\det J)^2} J (\hat{\tau} \circ F^{-1}) J^\top. \end{aligned}$$

Definition

Let $F : \hat{K} \rightarrow K$, $J(\hat{\mathbf{x}}) = \hat{\nabla}F(\hat{\mathbf{x}})$ its Jacobian. The *contravariant Piola transform* takes

$$\begin{aligned} \left(\hat{\Phi} : \hat{K} \rightarrow \mathbb{R}^d \right) &\mapsto \left(\mathcal{F}^{\text{div}}(\hat{\Phi}) = \Phi : K \rightarrow \mathbb{R}^d \right), \\ \mathcal{F}^{\text{div}}(\hat{\Phi}) &:= \frac{1}{\det J} J \hat{\Phi} \circ F^{-1}. \end{aligned}$$

The *double contravariant Piola transform* is

$$\begin{aligned} \left(\hat{\tau} : \hat{K} \rightarrow \mathbb{S} \right) &\mapsto \left(\mathcal{F}^{\text{div},\text{div}}(\hat{\tau}) = \tau : K \rightarrow \mathbb{S} \right), \\ \mathcal{F}^{\text{div},\text{div}}(\hat{\tau}) &:= \frac{1}{(\det J)^2} J (\hat{\tau} \circ F^{-1}) J^\top. \end{aligned}$$

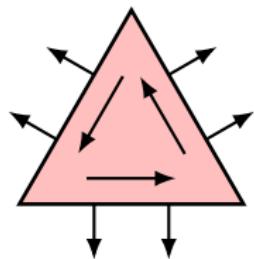
Fact

These are isomorphisms

$$H(\text{div}, \hat{K}) \xrightarrow{\sim} H(\text{div}, K), \quad H(\text{div}, \hat{K}; \mathbb{S}) \xrightarrow{\sim} H(\text{div}, K; \mathbb{S}).$$

The Mardal–Tai–Winther element

$$MTW(K) = \left\{ \Phi \in \mathcal{P}_3(K; \mathbb{R}^2) \mid \operatorname{div} \Phi \in \mathcal{P}_0(K), (\Phi \cdot \mathbf{n})|_{\mathbf{e}} \in \mathcal{P}_1(\mathbf{e}) \forall \text{ edges } \mathbf{e} \right\}$$

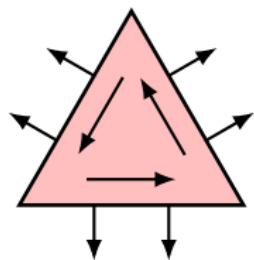


The Mardal–Tai–Winther element

$$MTW(K) = \left\{ \Phi \in \mathcal{P}_3(K; \mathbb{R}^2) \mid \operatorname{div} \Phi \in \mathcal{P}_0(K), (\Phi \cdot \mathbf{n})|_{\mathbf{e}} \in \mathcal{P}_1(\mathbf{e}) \forall \text{ edges } \mathbf{e} \right\}$$

Novelties:

- Discretises $H(\operatorname{div})$ and (nonconforming) $\mathbf{H}^1(\Omega)$

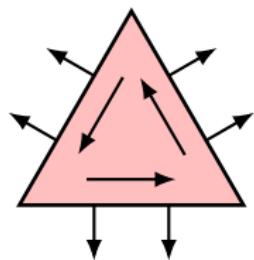


The Mardal–Tai–Winther element

$$MTW(K) = \{ \Phi \in \mathcal{P}_3(K; \mathbb{R}^2) \mid \operatorname{div} \Phi \in \mathcal{P}_0(K), (\Phi \cdot \mathbf{n})|_{\mathbf{e}} \in \mathcal{P}_1(\mathbf{e}) \text{ } \forall \text{ edges } \mathbf{e} \}$$

Novelties:

- Discretises $H(\operatorname{div})$ and (nonconforming) $\mathbf{H}^1(\Omega)$
- Stable for both Stokes and Darcy flow

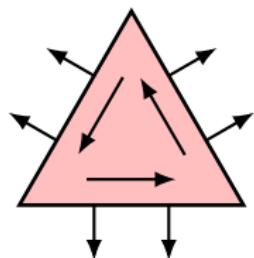


The Mardal–Tai–Winther element

$$MTW(K) = \left\{ \Phi \in \mathcal{P}_3(K; \mathbb{R}^2) \mid \operatorname{div} \Phi \in \mathcal{P}_0(K), (\Phi \cdot \mathbf{n})|_{\mathbf{e}} \in \mathcal{P}_1(\mathbf{e}) \forall \text{ edges } \mathbf{e} \right\}$$

Novelties:

- Discretises $H(\operatorname{div})$ and (nonconforming) $\mathbf{H}^1(\Omega)$
- Stable for both Stokes and Darcy flow
- Locking-free element for (poro)elasticity; discrete Korn inequality

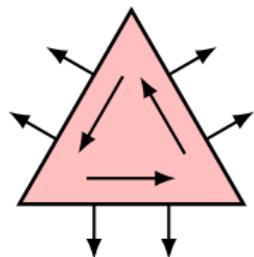


The Mardal–Tai–Winther element

$$MTW(K) = \left\{ \Phi \in \mathcal{P}_3(K; \mathbb{R}^2) \mid \operatorname{div} \Phi \in \mathcal{P}_0(K), (\Phi \cdot \mathbf{n})|_{\mathbf{e}} \in \mathcal{P}_1(\mathbf{e}) \forall \text{ edges } \mathbf{e} \right\}$$

Novelties:

- Discretises $H(\operatorname{div})$ and (nonconforming) $\mathbf{H}^1(\Omega)$
- Stable for both Stokes and Darcy flow
- Locking-free element for (poro)elasticity; discrete Korn inequality
- Divergence-free for Stokes when paired with $DG(0)$



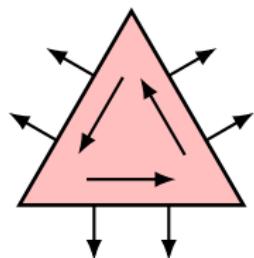
The Mardal–Tai–Winther element

$$MTW(K) = \{ \Phi \in \mathcal{P}_3(K; \mathbb{R}^2) \mid \operatorname{div} \Phi \in \mathcal{P}_0(K), (\Phi \cdot \mathbf{n})|_{\mathbf{e}} \in \mathcal{P}_1(\mathbf{e}) \forall \text{ edges } \mathbf{e} \}$$

Novelties:

- Discretises $H(\operatorname{div})$ and (nonconforming) $\mathbf{H}^1(\Omega)$
- Stable for both Stokes and Darcy flow
- Locking-free element for (poro)elasticity; discrete Korn inequality
- Divergence-free for Stokes when paired with $DG(0)$
- Discretises the 2D Stokes complex:

$$\mathbb{R} \xrightarrow{\subset} H^2(\Omega) \xrightarrow{\operatorname{curl}} \mathbf{H}^1(\Omega) \xrightarrow{\operatorname{div}} L^2(\Omega) \longrightarrow 0.$$





The Arnold–Winther stress elements

Conforming: $AW^c(K) = \{\tau \in \mathcal{P}_3(K; \mathbb{S}) \mid \operatorname{div} \tau \in \mathcal{P}_1(K; \mathbb{R}^2)\}$

Nonconforming: $AW^{nc}(K) = \{\tau \in \mathcal{P}_2(K; \mathbb{S}) \mid \mathbf{n} \cdot \tau \mathbf{n} \in \mathcal{P}_1(\mathbf{e}) \forall \text{ edges } \mathbf{e}\}$

paired with **DG(1)** for the displacement.



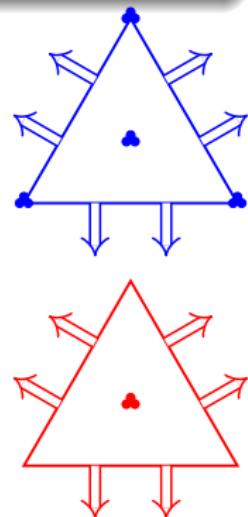
The Arnold–Winther stress elements

Conforming: $AW^c(K) = \{\tau \in \mathcal{P}_3(K; \mathbb{S}) \mid \operatorname{div} \tau \in \mathcal{P}_1(K; \mathbb{R}^2)\}$

Nonconforming: $AW^{nc}(K) = \{\tau \in \mathcal{P}_2(K; \mathbb{S}) \mid \mathbf{n} \cdot \tau \mathbf{n} \in \mathcal{P}_1(\mathbf{e}) \forall \text{ edges } \mathbf{e}\}$

paired with **DG(1)** for the displacement.

- Exact enforcement of the symmetry of the Cauchy stress.





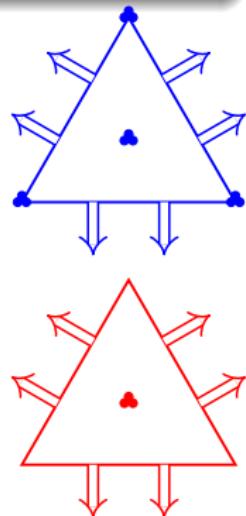
The Arnold–Winther stress elements

Conforming: $AW^c(K) = \{\tau \in \mathcal{P}_3(K; \mathbb{S}) \mid \operatorname{div} \tau \in \mathcal{P}_1(K; \mathbb{R}^2)\}$

Nonconforming: $AW^{nc}(K) = \{\tau \in \mathcal{P}_2(K; \mathbb{S}) \mid \mathbf{n} \cdot \tau \mathbf{n} \in \mathcal{P}_1(\mathbf{e}) \forall \text{ edges } \mathbf{e}\}$

paired with **DG(1)** for the displacement.

- Exact enforcement of the symmetry of the Cauchy stress.
- Stable and convergent for stress-displacement linear elasticity.





The Arnold–Winther stress elements

Conforming: $AW^c(K) = \{\tau \in \mathcal{P}_3(K; \mathbb{S}) \mid \operatorname{div} \tau \in \mathcal{P}_1(K; \mathbb{R}^2)\}$

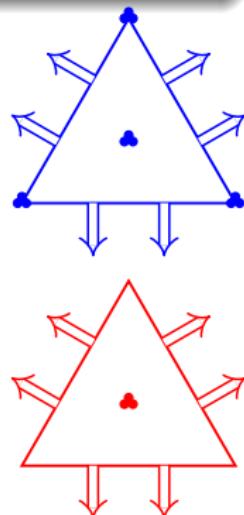
Nonconforming: $AW^{nc}(K) = \{\tau \in \mathcal{P}_2(K; \mathbb{S}) \mid \mathbf{n} \cdot \tau \mathbf{n} \in \mathcal{P}_1(\mathbf{e}) \forall \text{ edges } \mathbf{e}\}$

paired with **DG(1)** for the displacement.

- Exact enforcement of the symmetry of the Cauchy stress.
- Stable and convergent for stress-displacement linear elasticity.
- Discretise the 2D stress complex:

$$\begin{array}{ccccccc}
 0 & \longrightarrow & \mathcal{P}_1(\Omega) & \xrightarrow{\subset} & H^2(\Omega) & \xrightarrow{\text{airy}} & H(\operatorname{div}; \mathbb{S}) \\
 & & \downarrow \text{id} & & \downarrow I_h & & \downarrow \Pi_h \\
 0 & \longrightarrow & \mathcal{P}_1(\Omega) & \xrightarrow{\subset} & Q_h & \xrightarrow{\text{airy}} & \Sigma_h
 \end{array}$$

$$\begin{array}{ccccc}
 & & \xrightarrow{\operatorname{div}} & & 0 \\
 & & \downarrow P_h & & \\
 & & \Sigma_h & \xrightarrow{\operatorname{div}} & V_h \\
 & & \downarrow & & \downarrow \\
 & & & & 0.
 \end{array}$$





The Arnold–Winther stress elements

Conforming: $AW^c(K) = \{\tau \in \mathcal{P}_3(K; \mathbb{S}) \mid \operatorname{div} \tau \in \mathcal{P}_1(K; \mathbb{R}^2)\}$

Nonconforming: $AW^{nc}(K) = \{\tau \in \mathcal{P}_2(K; \mathbb{S}) \mid \mathbf{n} \cdot \tau \mathbf{n} \in \mathcal{P}_1(\mathbf{e}) \forall \text{ edges } \mathbf{e}\}$

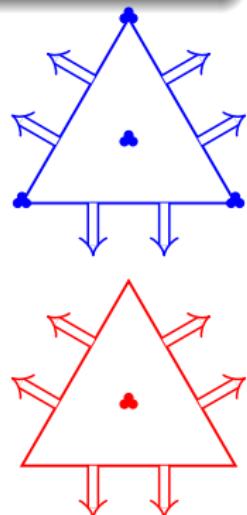
paired with **DG(1)** for the displacement.

- Exact enforcement of the symmetry of the Cauchy stress.
- Stable and convergent for stress-displacement linear elasticity.
- Discretise the 2D stress complex:

$$\begin{array}{ccccccc}
 0 & \longrightarrow & \mathcal{P}_1(\Omega) & \xrightarrow{\subset} & H^2(\Omega) & \xrightarrow{\text{airy}} & H(\operatorname{div}; \mathbb{S}) \\
 & & \downarrow \text{id} & & \downarrow I_h & & \downarrow \Pi_h \\
 0 & \longrightarrow & \mathcal{P}_1(\Omega) & \xrightarrow{\subset} & Q_h & \xrightarrow{\text{airy}} & \Sigma_h
 \end{array}$$

$$\begin{array}{ccccc}
 & & \xrightarrow{\operatorname{div}} & & 0 \\
 & & \downarrow P_h & & \\
 & & \Sigma_h & \xrightarrow{\operatorname{div}} & V_h \\
 & & \downarrow & & \downarrow \\
 & & & & 0.
 \end{array}$$

- **Almost never systematically implemented.**



Piola-inequivalent spaces

Denote:

- $\mathcal{F}^* : \hat{V} \rightarrow V$ a reference-to-physical Piola pullback
- $\hat{\Psi}, \Psi$ nodal bases for the MTW or AW spaces.

Then unfortunately,

$$\mathcal{F}^*(\hat{\Psi}) \neq \Psi, \quad \text{but} \quad \Psi = M\mathcal{F}^*(\hat{\Psi}) \text{ for some invertible } M.$$

Piola-inequivalent spaces



UNIVERSITY OF
OXFORD
Mathematical
Institute

Denote:

- $\mathcal{F}^* : \hat{V} \rightarrow V$ a reference-to-physical Piola pullback
- $\hat{\Psi}, \Psi$ nodal bases for the MTW or AW spaces.

Then unfortunately,

$$\mathcal{F}^*(\hat{\Psi}) \neq \Psi, \quad \text{but} \quad \Psi = M\mathcal{F}^*(\hat{\Psi}) \text{ for some invertible } M.$$

Similarly, define:

- pushforward $\mathcal{F}_* : V^* \rightarrow \hat{V}^*$
- sets of DOFs $\mathcal{L}, \hat{\mathcal{L}}$
then $\hat{\mathcal{L}} = P\mathcal{F}_*(\mathcal{L})$ for some invertible P .

Denote:

- $\mathcal{F}^* : \hat{V} \rightarrow V$ a reference-to-physical Piola pullback
- $\hat{\Psi}, \Psi$ nodal bases for the MTW or AW spaces.

Then unfortunately,

$$\mathcal{F}^*(\hat{\Psi}) \neq \Psi, \quad \text{but} \quad \Psi = M\mathcal{F}^*(\hat{\Psi}) \text{ for some invertible } M.$$

Similarly, define:

- pushforward $\mathcal{F}_* : V^* \rightarrow \hat{V}^*$
- sets of DOFs $\mathcal{L}, \hat{\mathcal{L}}$
then $\hat{\mathcal{L}} = P\mathcal{F}_*(\mathcal{L})$ for some invertible P .

Theorem [Kirby (2018)]

$$M = P^\top.$$

Denote:

- $\mathcal{F}^* : \hat{V} \rightarrow V$ a reference-to-physical Piola pullback
- $\hat{\Psi}, \Psi$ nodal bases for the MTW or AW spaces.

Then unfortunately,

$$\mathcal{F}^*(\hat{\Psi}) \neq \Psi, \quad \text{but} \quad \Psi = M\mathcal{F}^*(\hat{\Psi}) \text{ for some invertible } M.$$

Similarly, define:

- pushforward $\mathcal{F}_* : V^* \rightarrow \hat{V}^*$
- sets of DOFs $\mathcal{L}, \hat{\mathcal{L}}$
then $\hat{\mathcal{L}} = P\mathcal{F}_*(\mathcal{L})$ for some invertible P .

Theorem [Kirby (2018)]

$$M = P^\top.$$

Proposition [A., Farrell, Kirby (2020)]

Explicit construction of the (sparse) dual transformations P for the MTW , AW^c , and AW^{nc} spaces.

Implementation: the *MTW* element



Mathematical
Institute

Implementation was carried out in **Firedrake** .

Implementation was carried out in **Firedrake** .

A perturbed saddle point system

Seek $(u, p) \in (H_0(\text{div}) \cap \epsilon \mathbf{H}_0^1(\Omega)) \times L^2(\Omega)$ such that

$$\begin{aligned} (I - \epsilon^2 \Delta) u - \nabla p &= f && \text{in } \Omega, \\ \text{div } u &= g && \text{in } \Omega, \\ u &= h && \text{on } \Gamma_D, \\ \epsilon^2 \nabla u \mathbf{n} - p \mathbf{n} &= 0 && \text{on } \Gamma_N. \end{aligned}$$

$\epsilon = 1$: Stokes-like incompressible flow.

$\epsilon \rightarrow 0$: Darcy flow (\sim mixed Poisson).

Implementation was carried out in **Firedrake** 🚀.

A perturbed saddle point system

Seek $(u, p) \in (H_0(\text{div}) \cap \epsilon \mathbf{H}_0^1(\Omega)) \times L^2(\Omega)$ such that

$$\begin{aligned} (I - \epsilon^2 \Delta) u - \nabla p &= f && \text{in } \Omega, \\ \text{div } u &= g && \text{in } \Omega, \\ u &= h && \text{on } \Gamma_D, \\ \epsilon^2 \nabla u \mathbf{n} - p \mathbf{n} &= 0 && \text{on } \Gamma_N. \end{aligned}$$

$\epsilon = 1$: Stokes-like incompressible flow.

$\epsilon \rightarrow 0$: Darcy flow (\sim mixed Poisson).

We validate robustness with respect to ϵ using a smooth MMS on $\Omega = (0, 1)^2$.

The *MTW* element: ϵ -independent MMS convergence rates



Mathematical
Institute

$\epsilon \setminus N$	$ $	2^0	2^1	2^2	2^3	2^4	2^5	$ $	EOC
1		0.00456896	0.00128355	0.000341183	8.8577e-05	2.26311e-05	5.72514e-06		1.92807
2^{-2}		0.00447605	0.00126505	0.000335227	8.68331e-05	2.21707e-05	5.60825e-06		1.92809
2^{-4}		0.00421902	0.00120629	0.000319928	8.22134e-05	2.09019e-05	5.2806e-06		1.9284
2^{-6}		0.00405483	0.00113654	0.000305674	7.96031e-05	2.02428e-05	5.10031e-06		1.92697
2^{-8}		0.0040504	0.00112421	0.000296652	7.67045e-05	1.97471e-05	5.02906e-06		1.93071
2^{-10}		0.00405058	0.00112407	0.000296248	7.60249e-05	1.92762e-05	4.88509e-06		1.9391
0		0.00405059	0.00112407	0.000296246	7.60168e-05	1.92522e-05	4.84429e-06		1.94153

L^2 errors and convergence rates of *MTW* velocity for a range of ϵ .

$\epsilon \setminus N$	$ $	2^0	2^1	2^2	2^3	2^4	2^5	$ $	EOC
1		0.430242	0.200198	0.102848	0.051765	0.0259237	0.0129668		1.01045
2^{-2}		0.420754	0.198049	0.102341	0.051599	0.0258535	0.0129335		1.00476
2^{-4}		0.420711	0.19804	0.102339	0.0515984	0.0258533	0.0129334		1.00473
2^{-6}		0.420711	0.19804	0.102339	0.0515983	0.0258533	0.0129334		1.00473
2^{-8}		0.420711	0.19804	0.102339	0.0515983	0.0258533	0.0129334		1.00473
2^{-10}		0.420711	0.19804	0.102339	0.0515983	0.0258533	0.0129334		1.00473
0		0.420711	0.19804	0.102339	0.0515983	0.0258533	0.0129334		1.00473

L^2 pressure errors and convergence rates.

The Hellinger–Reissner principle

Seek a stress-displacement pair $(\sigma, u) \in H(\text{div}; \mathbb{S}) \times \mathbf{L}^2(\Omega)$ such that

$$\begin{aligned}\mathcal{A}\sigma &= \varepsilon(u) && \text{in } \Omega, \\ \text{div } \sigma &= f && \text{in } \Omega, \\ u &= u_0 && \text{on } \Gamma_D, \\ \sigma \mathbf{n} &= g && \text{on } \Gamma_N,\end{aligned}$$

where $\mathcal{A} = \mathcal{A}(\mu, \lambda)$ denotes the compliance tensor.

We validate the implementation again using a smooth MMS.

Arnold–Winther elements: MMS convergence rates



Mathematical
Institute

N	u error	u EOC	σ error	σ EOC	$\text{div}_h \sigma$ error	$\text{div}_h \sigma$ EOC
2^1	0.10522	–	0.490015	–	0.832183	–
2^2	0.0278746	1.91638	0.209729	1.2243	0.267865	1.63539
2^3	0.00707398	1.97836	0.0890996	1.23504	0.0714705	1.90609
2^4	0.00177271	1.99656	0.0412454	1.11118	0.0181626	1.97638
2^5	0.000442977	2.00066	0.0199779	1.04583	0.00455929	1.99409

L^2 errors and convergence rates for AW^{nc} , at Poisson ratio $\nu = 0.3$.

N	u error	u EOC	σ error	σ EOC	$\text{div} \sigma$ error	$\text{div} \sigma$ EOC
2^0	4.94678	–	0.00816494	–	0.037794	–
2^1	1.0283	2.26623	0.0010553	2.95179	0.01005	1.91095
2^2	0.0826871	3.63646	0.000129246	3.02946	0.0025538	1.97649
2^3	0.00561489	3.88033	1.59231e-05	3.02093	0.000641093	1.99404
2^4	0.000365775	3.94023	1.98093e-06	3.00687	0.00016044	1.9985
2^5	2.7322e-05	3.74282	2.47482e-07	3.00078	4.01203e-05	1.99963

AW^c , near the incompressible limit $\nu = 0.49999$.

To enforce the traction condition

$$\sigma \mathbf{n} = g \quad \text{on } \Gamma_N$$

which is **particularly difficult with AW elements** [Carstensen et al. (2008)],

To enforce the traction condition

$$\sigma \mathbf{n} = g \quad \text{on } \Gamma_N$$

which is **particularly difficult with AW elements** [Carstensen et al. (2008)], and to aid multigrid preconditioning, seek stationary points of

$$\begin{aligned} \mathcal{H}_{h,\gamma,\omega}(\sigma_h, u_h) := & \int_{\Omega} \frac{1}{2} \mathcal{A} \sigma_h : \sigma_h + (\operatorname{div} \sigma_h - f) \cdot u_h \\ & - \int_{\Gamma_N} (\sigma_h \mathbf{n} - g) \cdot u_h \, ds + \frac{\gamma}{2h} \int_{\Gamma_N} \|\sigma_h \mathbf{n} - g\|^2 \, ds \end{aligned} .$$

- Nitsche penalty for the traction condition,

To enforce the traction condition

$$\sigma \mathbf{n} = g \quad \text{on } \Gamma_N$$

which is **particularly difficult with AW elements** [Carstensen et al. (2008)], and to aid multigrid preconditioning, seek stationary points of

$$\begin{aligned} \mathcal{H}_{h,\gamma,\omega}(\sigma_h, u_h) := & \int_{\Omega} \frac{1}{2} \mathcal{A} \sigma_h : \sigma_h + (\operatorname{div} \sigma_h - f) \cdot u_h \\ & - \int_{\Gamma_N} (\sigma_h \mathbf{n} - g) \cdot u_h \, ds + \frac{\gamma}{2h} \int_{\Gamma_N} \|\sigma_h \mathbf{n} - g\|^2 \, ds + \frac{\omega}{2} \int_{\Omega} \|\operatorname{div} \sigma_h - f\|^2 \, dx. \end{aligned}$$

- Nitsche penalty for the traction condition,
- augmented Lagrangian penalty to control the Schur complement.

To enforce the traction condition

$$\sigma \mathbf{n} = g \quad \text{on } \Gamma_N$$

which is **particularly difficult with AW elements** [Carstensen et al. (2008)], and to aid multigrid preconditioning, seek stationary points of

$$\begin{aligned} \mathcal{H}_{h,\gamma,\omega}(\sigma_h, u_h) := & \int_{\Omega} \frac{1}{2} \mathcal{A} \sigma_h : \sigma_h + (\operatorname{div} \sigma_h - f) \cdot u_h \\ & - \int_{\Gamma_N} (\sigma_h \mathbf{n} - g) \cdot u_h \, ds + \frac{\gamma}{2h} \int_{\Gamma_N} \|\sigma_h \mathbf{n} - g\|^2 \, ds + \frac{\omega}{2} \int_{\Omega} \|\operatorname{div} \sigma_h - f\|^2 \, dx. \end{aligned}$$

- Nitsche penalty for the traction condition,
- augmented Lagrangian penalty to control the Schur complement.

Patch-based additive Schwarz smoother [e.g. Schöberl (1999)]

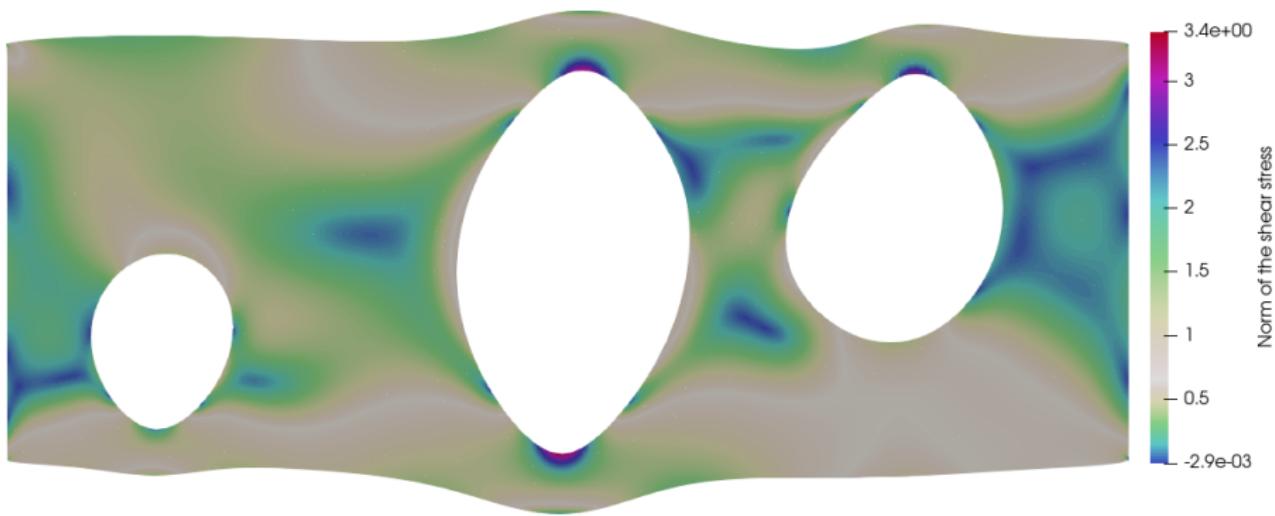
We employ the *vertex-star iteration* to precondition the augmented stress block after block factorisation, applied by PCASM.

Arnold–Winther elements for linear elasticity

Numerical results



Mathematical
Institute



A traction-free condition except at both ends, coloured by the shear stress, near the incompressible limit ($\nu = 0.499999$); 1.14×10^6 DOFs using AW^{nc} . Considered in [Li (2018)].

Take-home messages



- We have generalised contravariant Piola transformation theory to Piola-inequivalent elements.

- We have generalised contravariant Piola transformation theory to Piola-inequivalent elements.
- Robust implementation of:
 - ▶ Mardal–Tai–Winther elements for Stokes–Darcy flow.
 - ▶ Arnold–Winther elements for stress-displacement linear elasticity.

- We have generalised contravariant Piola transformation theory to Piola-inequivalent elements.
- Robust implementation of:
 - ▶ Mardal–Tai–Winther elements for Stokes–Darcy flow.
 - ▶ Arnold–Winther elements for stress-displacement linear elasticity.
- Conformity to complexes allows for the deployment of patch-based multigrid smoothers.

- We have generalised contravariant Piola transformation theory to Piola-inequivalent elements.
- Robust implementation of:
 - ▶ Mardal–Tai–Winther elements for Stokes–Darcy flow.
 - ▶ Arnold–Winther elements for stress-displacement linear elasticity.
- Conformity to complexes allows for the deployment of patch-based multigrid smoothers.
- Our approach is inexpensive, composing neatly with the existing software stack.

- We have generalised contravariant Piola transformation theory to Piola-inequivalent elements.
- Robust implementation of:
 - ▶ Mardal–Tai–Winther elements for Stokes–Darcy flow.
 - ▶ Arnold–Winther elements for stress-displacement linear elasticity.
- Conformity to complexes allows for the deployment of patch-based multigrid smoothers.
- Our approach is inexpensive, composing neatly with the existing software stack.

Thanks.