



Nonlocal UFL: Finite elements for Helmholtz equations with a nonlocal boundary condition

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Order of Presentation

Motivating Problem: Helmholtz scattering

A nonlocal boundary condition

Nonlocal UFL

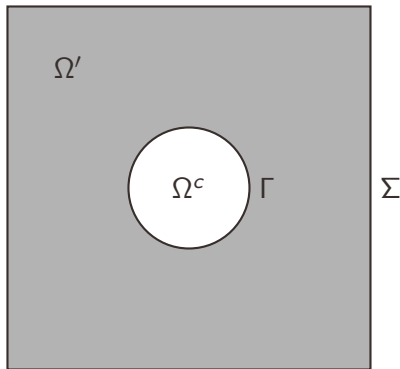
Numerical Results



Thanks to...

- ▶ NSF 1525697, 1909176
- ▶ The U.S. Department of Energy, Office of Science, Office of Advanced Scientific Computing Research, Department of Energy Computational Science Graduate Fellowship under Award Number DE-SC0021110
- ▶ Luke Olson (UIUC)

Exterior scattering¹



- Model waves reflecting off of obstacle Γ

$$\begin{cases} -\Delta u - \kappa^2 u = 0, & \mathbb{R}^d \setminus \Omega^c \\ \frac{\partial u}{\partial n} = f, & \Gamma \end{cases}$$

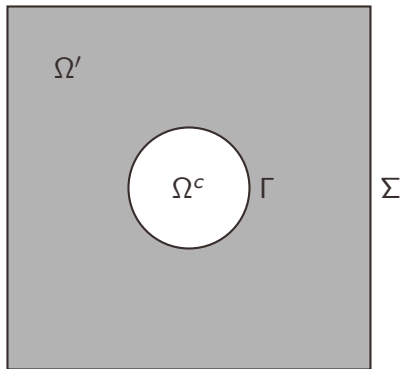
- *Without* any spurious reflections from infinity

$$\lim_{r \rightarrow \infty} r^{(d-1)/2} \left(\frac{\partial u}{\partial r} - i\kappa u \right) = 0$$

- In some finite domain of interest $\Omega' \subseteq \mathbb{R}^d \setminus \Omega^c$ bounded by Σ .

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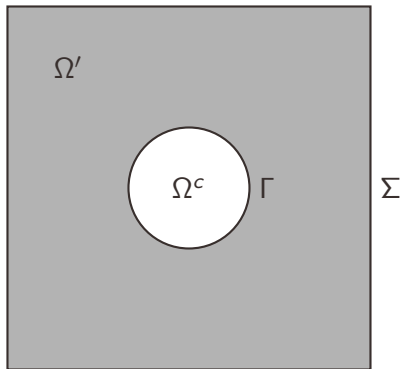
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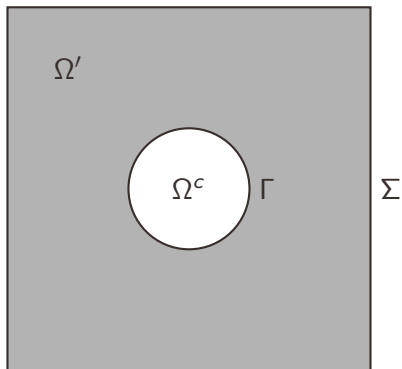
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Exterior scattering: computational problem



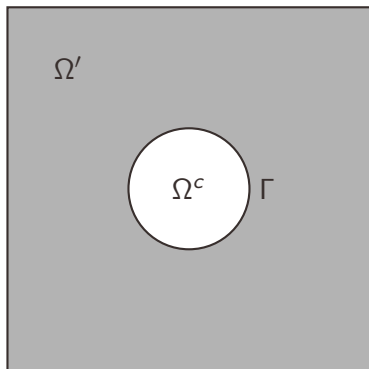
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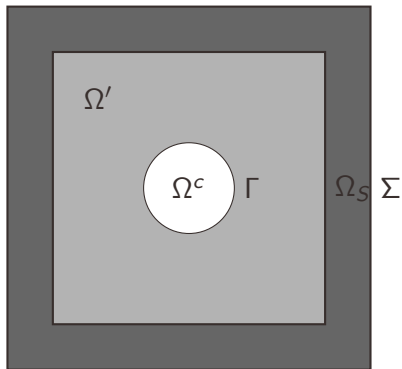
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Exterior scattering: Perfectly Matched Layers (PML)³



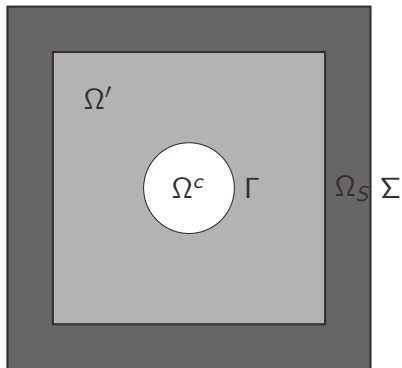
$$\begin{cases} -\nabla \cdot \beta(\mathbf{x}) \nabla u - \kappa^2 u = 0, & \Omega' \\ \frac{\partial u}{\partial n} = f, & \Gamma \\ u = 0, & \Sigma \end{cases}$$

- ▶ Ω' : $\beta = I$, satisfies original equation
- ▶ Ω_S : β is a complex-valued coordinate transform to cause exponential decay in oscillating waves
- ▶ **Preconditioning is difficult!**²

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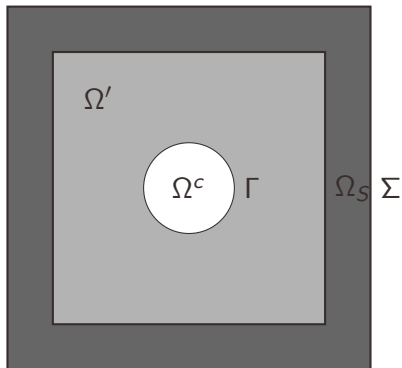
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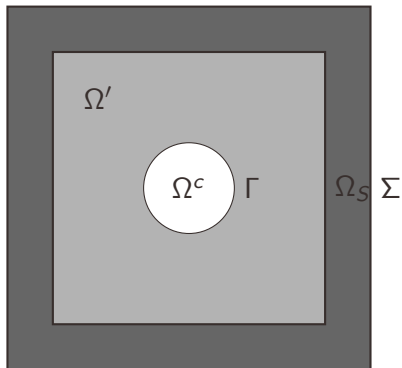
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Integral form of the solution

Using the Helmholtz Green's function

$$\mathcal{K}(x) = \frac{i}{4\pi |x|} e^{i\kappa|x|},$$

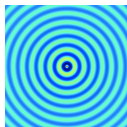


Figure: \mathcal{K} in 2D

the *true solution* satisfies⁴

$$u(x) = D(u)(x) - S\left(\frac{\partial u}{\partial n}\right)(x), \quad x \in \Omega'$$

where

$$D(u)(x) = \int_{\Gamma} \left(\frac{\partial}{\partial n} \mathcal{K}(x-y) \right) u(y) dy,$$

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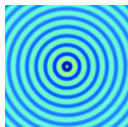


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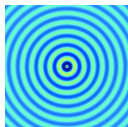


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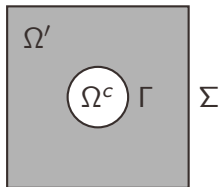
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Exterior scattering



Exact boundary conditions

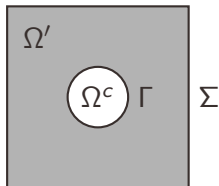
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Variational Form:

For all $v \in H^1(\Omega')$

$$\begin{aligned} (\nabla u, \nabla v) - \kappa^2 (u, v) - i\kappa \langle u, v \rangle_{\Sigma} + \langle (i\kappa - \frac{\partial}{\partial n}) D(u), v \rangle_{\Sigma} \\ = \langle f, v \rangle_{\Gamma} + \langle (i\kappa - \frac{\partial}{\partial n}) S(f), v \rangle_{\Sigma} \end{aligned}$$

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Theory

- ▶ a is a bounded bilinear form on $H^1 \times H^1$
- ▶ F is a bounded linear functional on H^1
- ▶ Gårding inequality. There exist M and an $\alpha > 0$ such that

$$\operatorname{Re}(a(u, u)) + M \|u\|^2 \geq \alpha \|u\|_{H^1(\Omega)}^2.$$

- ▶ For $h \leq h_0$, we have optimal-order H^1 and L^2 error estimates.⁵

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Nonlocal operations in UFL

► *Recall:*

$$D(u)(x) = \int_{\Gamma} \frac{\partial}{\partial n} \mathcal{K}(x - y) u(y) dy, \quad x \in \Sigma$$

- *Problem:* Nonlocal operations have large support (all of Σ !)
 - This makes our stiffness matrix dense, especially in 3D
 - *Solution:* Firedrake's matrix-free evaluation
- *Problem:* Naive evaluation of layer potentials is slow:
 - $\text{ndof}(\Gamma) \cdot \text{ndof}(\Sigma)$
 - *Solution:* Fast multipole methods (FMM)⁶: use the structure of \mathcal{K} to compute the potential in *linear time* with low-rank approximations

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Nonlocal operations in UFL: Marshalling pytential⁸

- ▶ Build `LayerPotential` as a UFL External Operator⁷
 - ✓ Build pytential representation of domain of interest
 - ✓ Build pytential representation of function space
 - ✓ Build efficient converter between pytential and firedrake representations
 - Fully support automatic differentiation
- ▶ Evaluation of $\langle (i\kappa - \frac{\partial}{\partial n})D(u), v \rangle_{\Sigma}$
 - ✓ `LayerPotential` evaluates $D(u)$ (automatically uses pytential, which employs FMM to compute the potential)
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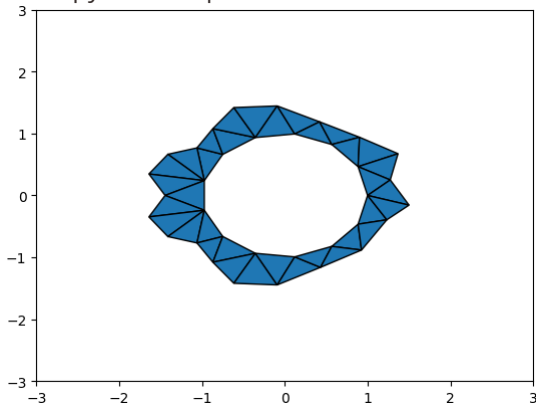
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Solving the system with Firedrake

Extend UFL:

$$a(u, v) = (\nabla u, \nabla v) - \kappa^2 (u, v) - i\kappa \langle u, v \rangle_{\Sigma} + \langle (i\kappa - \frac{\partial}{\partial n}) D(u)v \rangle_{\Sigma}$$



Solving the system with Firedrake

Extend UFL:

$$a(u, v) = (\nabla u, \nabla v) - \kappa^2 (u, v) - i\kappa \langle u, v \rangle_{\Sigma} + \langle (i\kappa - \frac{\partial}{\partial n}) D(u) v \rangle_{\Sigma}$$

Will be written as:

```
Du = DoubleLayerPotential(u, HelmholtzKernel(dim=2),
                           source=gamma, target=sigma)
a = inner(grad(u), grad(v)) * dx - \
    kappa**2 * inner(u, v) * dx - \
    i * kappa * inner(u, v) * ds(sigma) + \
    i * kappa * inner(Du, v) * ds(sigma) - \
    inner(dot(grad(Du), n), v) * ds(sigma)
```



Solving the system with Firedrake

Extend UFL:

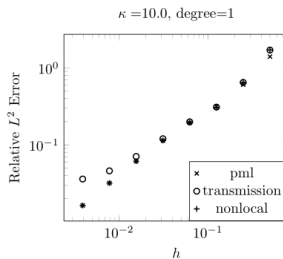
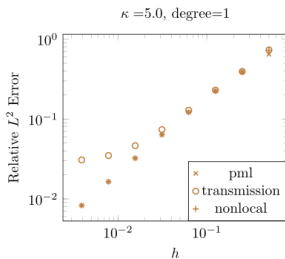
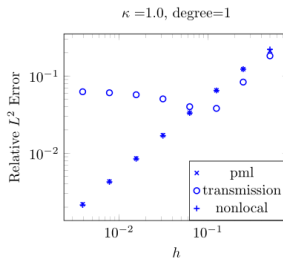
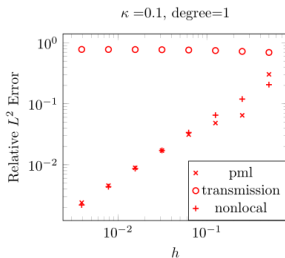
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```

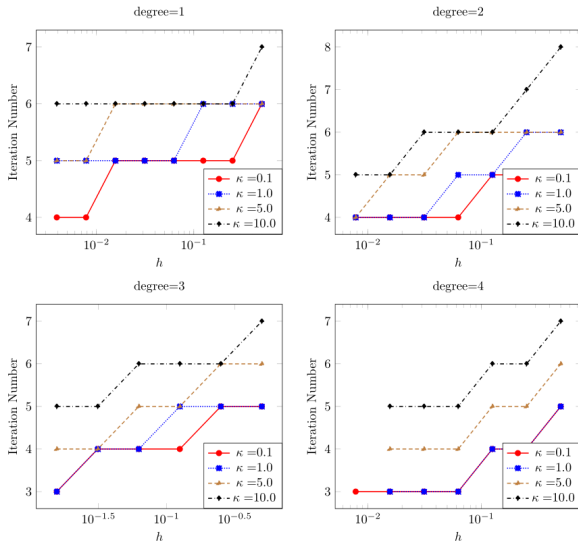


Numerical results: 2D





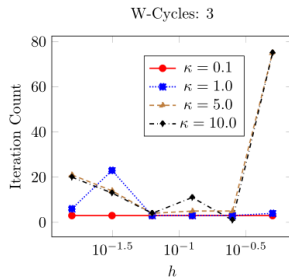
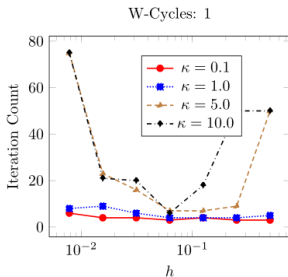
Preconditioning: LU of local part





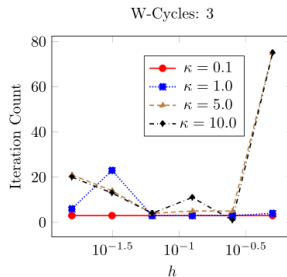
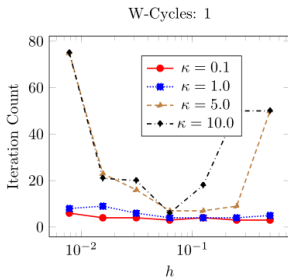
Preconditioning: PyAMG

- If we can find a good preconditioner for the local problem, we get a good preconditioner for the nonlocal problem
- PyAMG: precondition with plane waves



Preconditioning: PyAMG

- If we can find a good preconditioner for the local problem, we get a good preconditioner for the nonlocal problem
- PyAMG: precondition with plane waves





Conclusion

Results

- ▶ Novel nonlocal boundary condition
 - Error estimates⁹
- ▶ Extension of UFL to efficiently handle nonlocal operators
- ▶ Numerical experiments demonstrating optimal-order convergence
- ▶ Investigation into preconditioners

Coming Soon

- ▶ Full implementation of LayerPotentials and VolumePotential¹⁰s in UFL as External Operator¹¹s
- ▶ General theory for this method and application to more problems

¹⁰Kirby, Klöckner, and Sepanski 2021.

¹¹X. Wei, *IEM-FEM Coupling*: <https://fenics2021.com/talks/wei.html>

¹²N. Bouziani, *External Operators*: <https://fenics2021.com/talks/bouziani.html>



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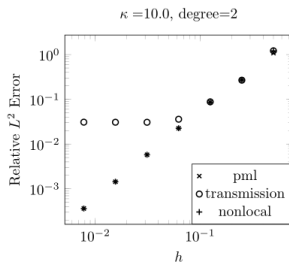
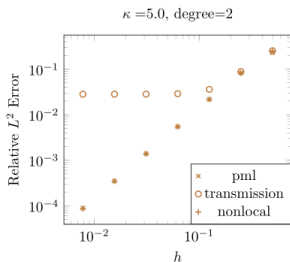
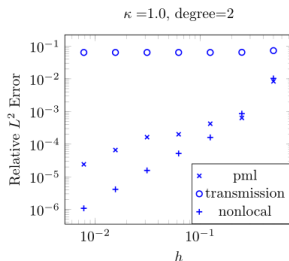
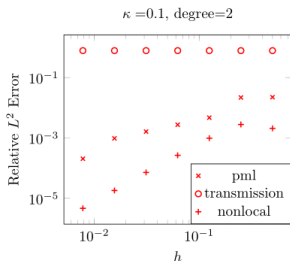
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Backup Slides

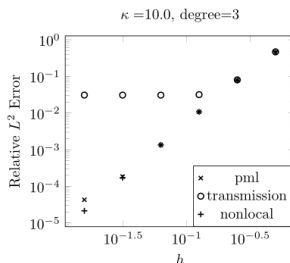
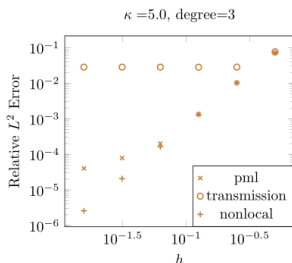
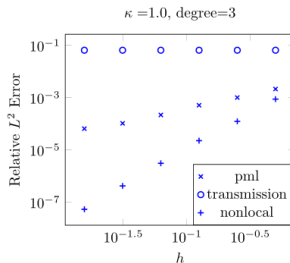
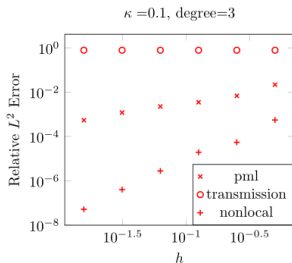


Numerical results: 2D, degree 2



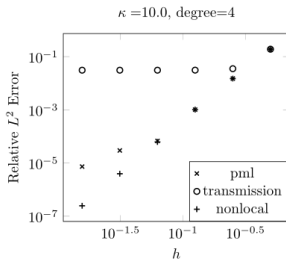
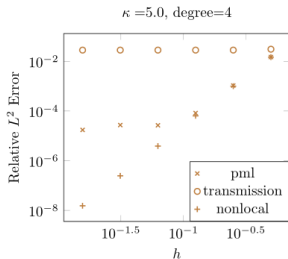
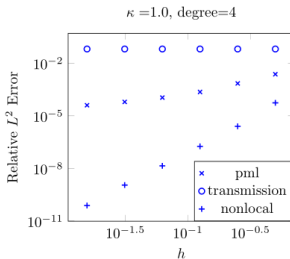
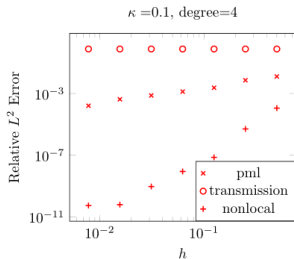


Numerical results: 2D, degree 3





Numerical results: 2D, degree 4





Numerical results: 3D, degree 1

