

Local a posteriori error estimates for the spectral fractional Laplacian

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DRIVEN



The spectral fractional Laplacian

- The spectral fractional Laplacian
 - Contribution
 - Discretization
 - A posteriori error estimation
 - Numerical results

The spectral fractional Laplacian

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The spectral fractional Laplacian

Let $\Omega \subset \mathbb{R}^d$, $\alpha \in (0, 2)$ and $f \in L^2(\Omega)$.

$$(-\Delta)^{\alpha/2} u = f \quad \text{in } \Omega, \quad u = 0 \quad \text{on } \partial\Omega. \quad (1)$$

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Let $\{\psi_i, \lambda_i\}_{i=1}^{+\infty} \subset L^2(\Omega) \times \mathbb{R}^+$ be such that

$$-\Delta\psi_i = \lambda_i\psi_i \quad \text{in } \Omega, \quad \psi_i = 0 \quad \text{on } \partial\Omega, \quad \forall i = 1, \dots, +\infty. \quad (2)$$

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The solution u of (1) is defined by

$$u := \sum_{i=1}^{+\infty} \lambda_i^{-\alpha/2} (f, \psi_i)_{L^2}. \quad (3)$$

Contribution

- The spectral fractional Laplacian

- **Contribution**

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Contribution

We present the first a posteriori error estimator for a numerical method presented in [Bonito and Pasciak, 2015] for solving the spectral fractional Laplacian.

Discretization

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Discretization

How to solve (1) numerically ?

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Using an **integral representation** of the solution

$$u = C_\alpha \int_{-\infty}^{+\infty} e^{\alpha y} u_y \, dy, \quad (4)$$

where u_y is solution to

$$e^{2y} \int_{\Omega} \nabla u_y \cdot \nabla v + \int_{\Omega} u_y v = \int_{\Omega} f v, \quad \forall v \in H_0^1(\Omega). \quad (5)$$

Discretization

- Quadrature discretization: given a quadrature rule $\{\omega_l, y_l\}_{l=-N}^N$,

$$u = C_\alpha \int_{-\infty}^{+\infty} e^{\alpha y} u_y \, dy \approx C_\alpha \sum_{l=-N}^N \omega_l e^{\alpha y_l} u_{y_l} =: u^N. \quad (6)$$

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- **Finite element discretization:** given a mesh \mathcal{T}_h on Ω and V_h a FE space,

$$u \approx C_\alpha \sum_{l=-N}^N \omega_l e^{\alpha y_l} u_{h,y_l} =: u_h^N, \quad (7)$$

where u_{h,y_l} solves

$$e^{2y_l} \int_{\Omega} \nabla u_{h,y_l} \cdot \nabla v_h + \int_{\Omega} u_{h,y_l} v_h = \int_{\Omega} f v_h \quad \forall v_h \in V_h. \quad (8)$$

A posteriori error estimation

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A posteriori error estimation

We neglect the quadrature discretization error and we focus on the FE discretization error

$$\eta \approx \|u - u_h^N\|_{L^2}. \quad (9)$$

A posteriori error estimation

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$$e^{2y} \int_T \nabla w_{T,y_l} \cdot \nabla v_T + \int_T w_{T,y_l} v_T = R_T(v_T) \quad \forall v_T \in V^{\text{bw}}(T). \quad (10)$$

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The local fractional Bank–Weiser solution is given by

$$w_T := C_\alpha \sum_{l=-N}^N \omega_l e^{\alpha y_l} w_{T,y_l}. \quad (11)$$

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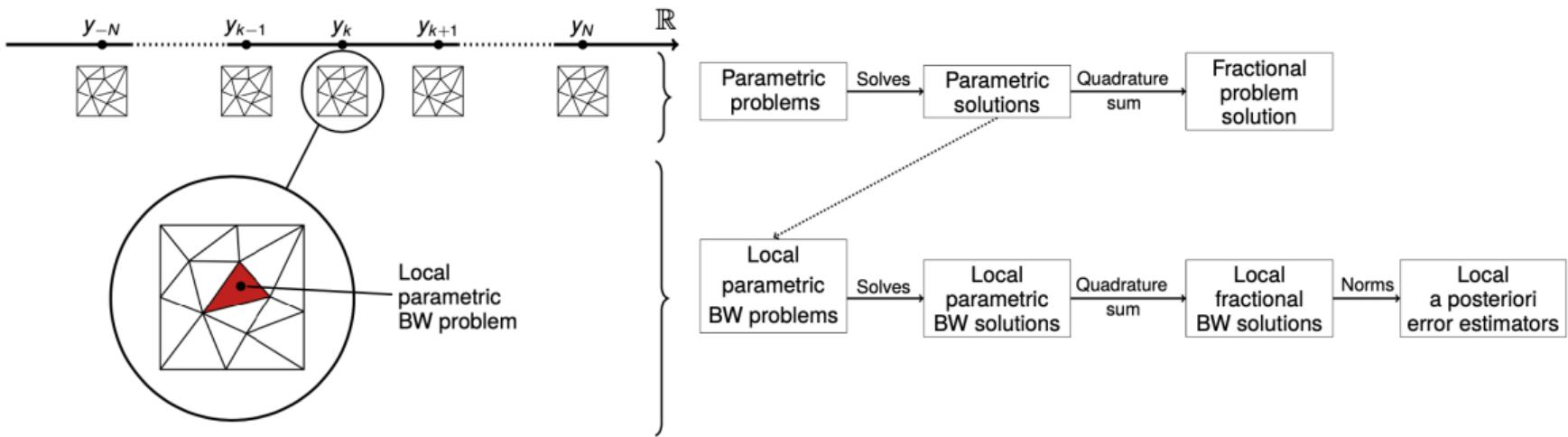
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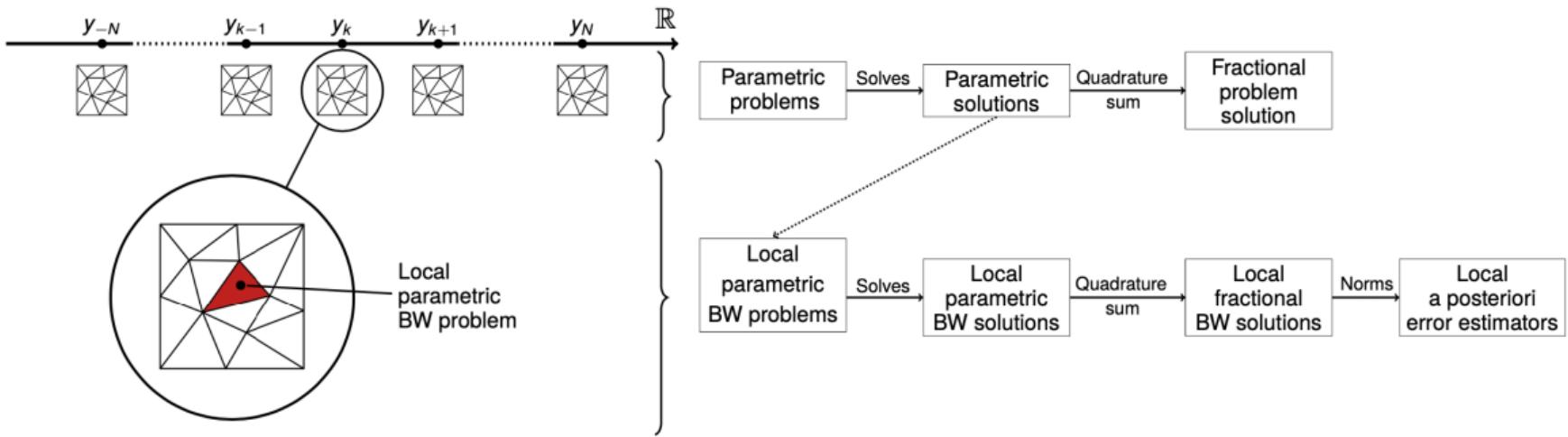
The local and global Bank–Weiser estimators are given by

$$\eta_{\text{bw},T} := \|w_T\|_{L^2(T)}, \quad \eta_{\text{bw}}^2 := \sum_{T \in \mathcal{T}_h} \|w_T\|_{L^2(T)}^2. \quad (12)$$

A posteriori error estimation



A posteriori error estimation

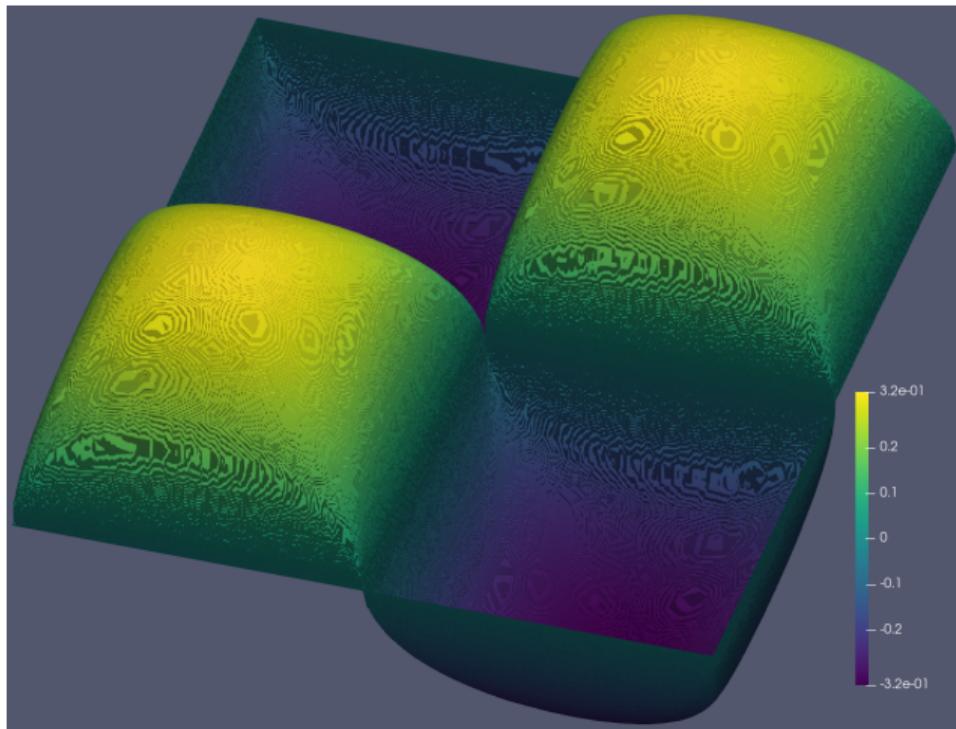


Fully local and fully parallelizable.

Numerical results

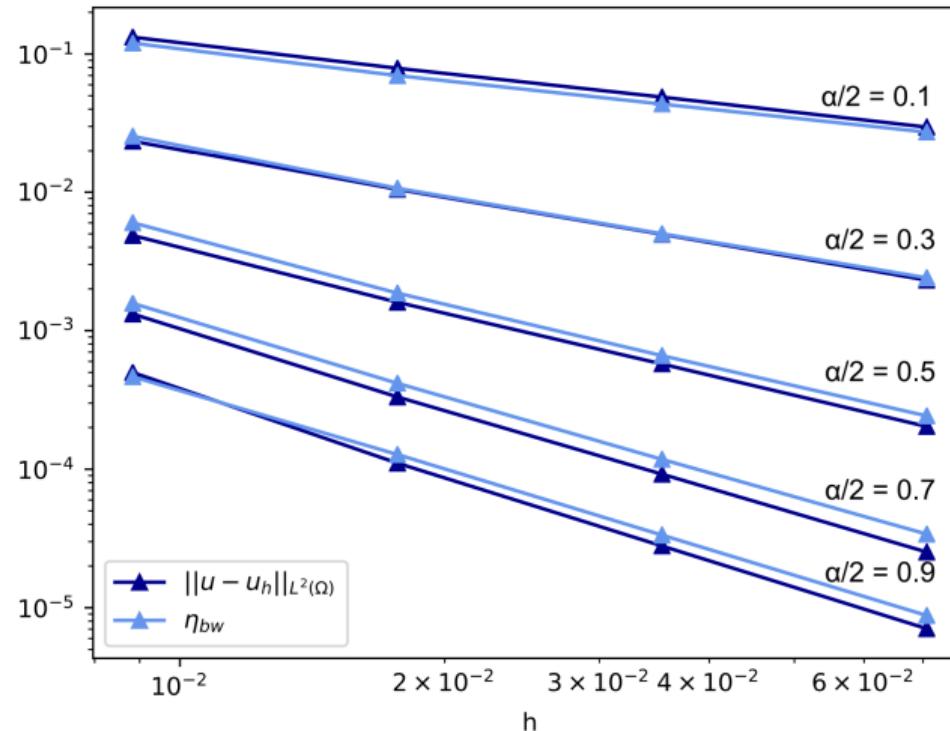
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Numerical results



Numerical results

Uniform mesh refinement.



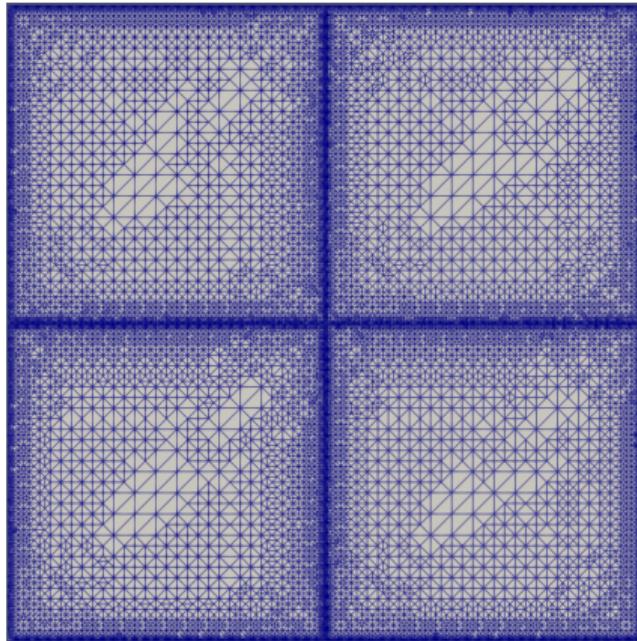
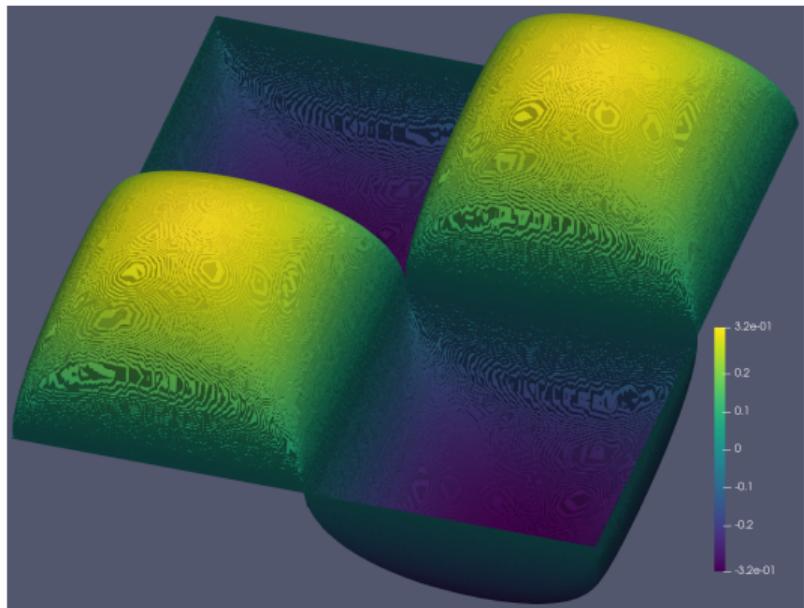
Numerical results

Uniform mesh refinement[Bonito and Pasciak, 2015].

Frac. pow.	0.1	0.3	0.5	0.7	0.9
Th. slope	0.7	1.1	1.5	1.9	2.0
Err. slope	0.71	1.11	1.52	1.9	2.04
Est. slope	0.71	1.13	1.54	1.84	1.91

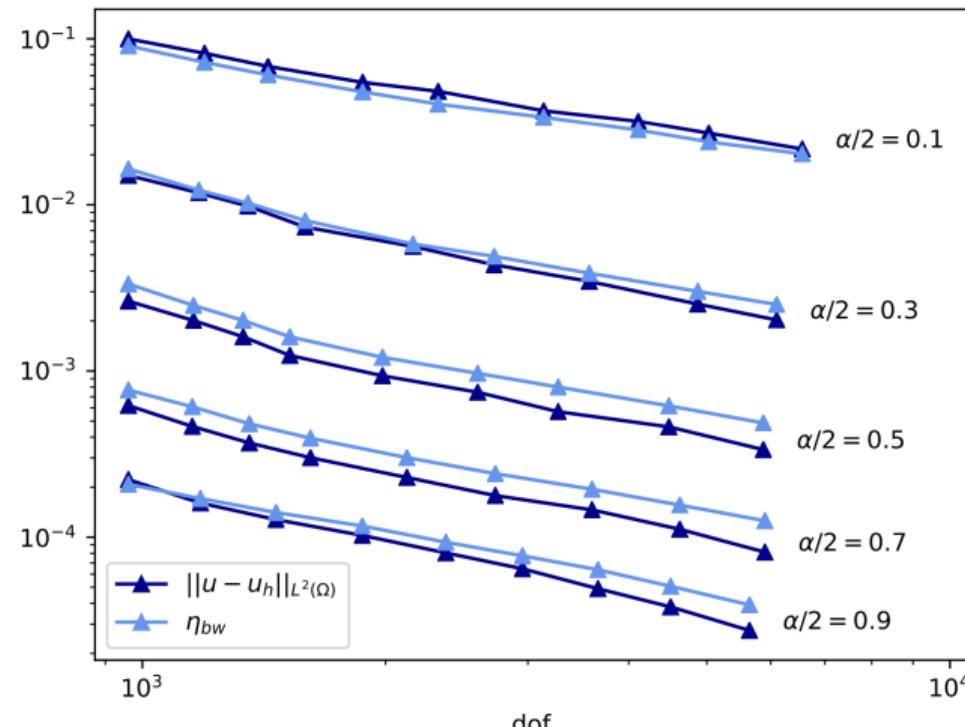
Numerical results

Adaptive mesh refinement.



Numerical results

Adaptive mesh refinement.



Numerical results

Adaptive mesh refinement.

Frac. pow.	0.1	0.3	0.5	0.7	0.9
Th. slope (unif.)	0.35	0.55	0.75	0.95	1.0
Err. slope (adapt.)	0.71	1.13	1.54	1.84	1.91
Est. slope (adapt.)	0.72	1.11	1.52	1.9	2.04

References |



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Math. Comput., 44(170):283–301.



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Thank you for your attention!



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